Toward Zero-waste Terabit Networked Systems

Liangcheng (LC) Yu





Ever-increasing user applications



















Latency-critical

Applications



Application

Machine Learning

Video Streaming

Network systems, a packet forwarding engine

































Network system

Networks serve to forward user data

Network systems, a packet forwarding engine





























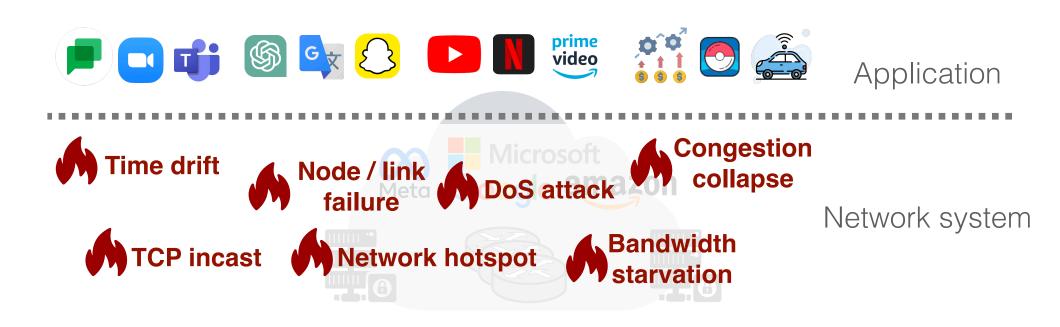




Network system

Networks serve to forward user data

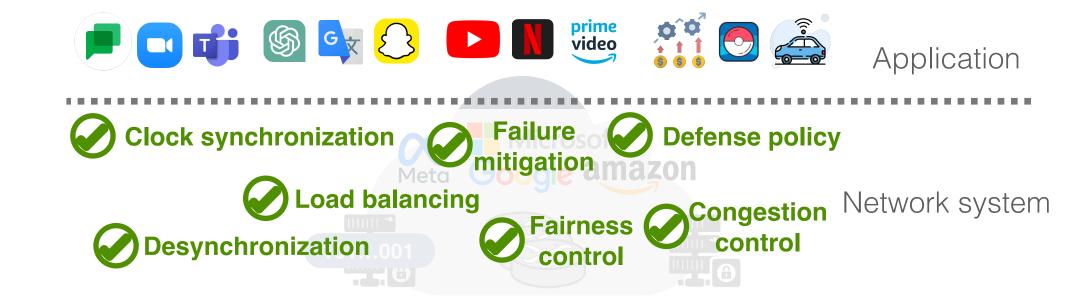
Today, networks are far more complex!



Networks serve to forward user data

Today, networks are far more complex!

...must handle out-of-control events!



Networks serve to **forward user data**

Today, networks are far more complex!

...a vast array of control tasks















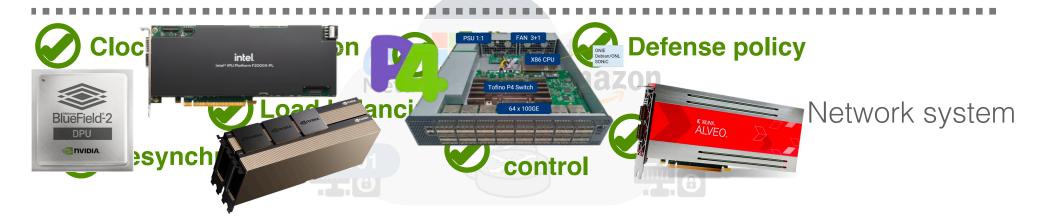












Networks serve to forward user data

Today, networks are far more complex!

...a vast array of control tasks

...in-network computation w/ emerging HW accelerators

...and more!

























Application

Today, network systems are **more than** just about **data forwarding!**

Networks serve to forward user data

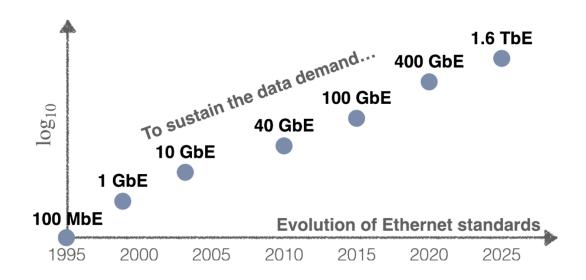
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...a vast array of control tasks

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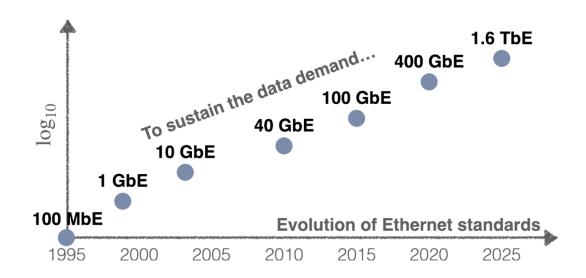
..and more!

Trend toward terabit speed...



The speed of networking is *outpacing* many others

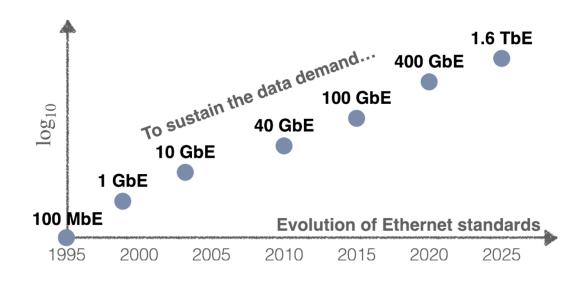
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Great for application data transfer

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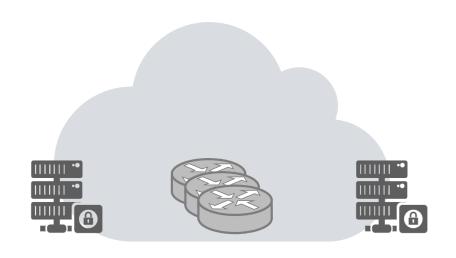


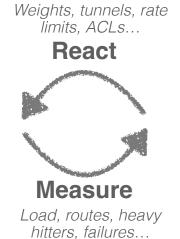
The speed of networking is *outpacing* many others

Great for application data transfer

... problematic for other tasks!

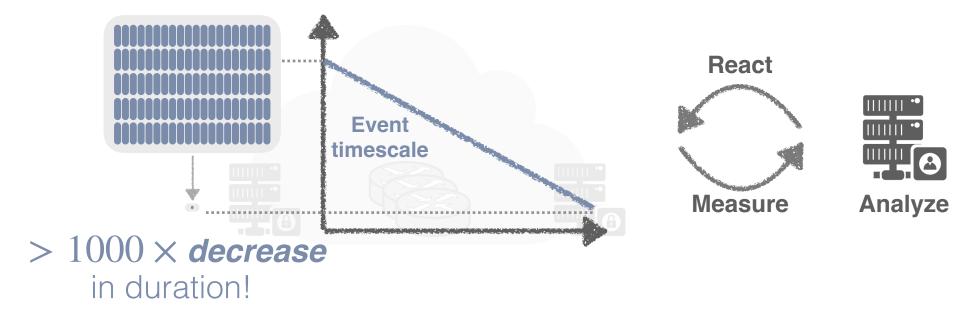
Network control function as an example

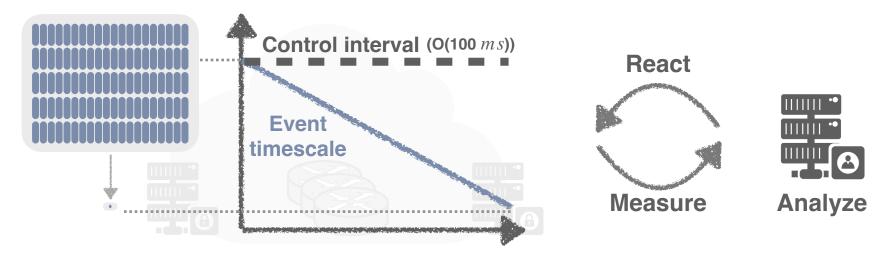




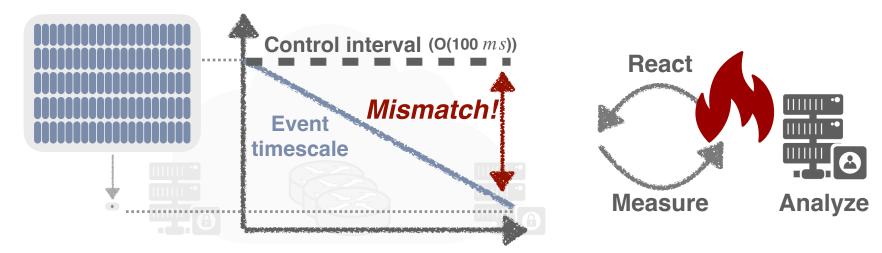


Network control function as an example



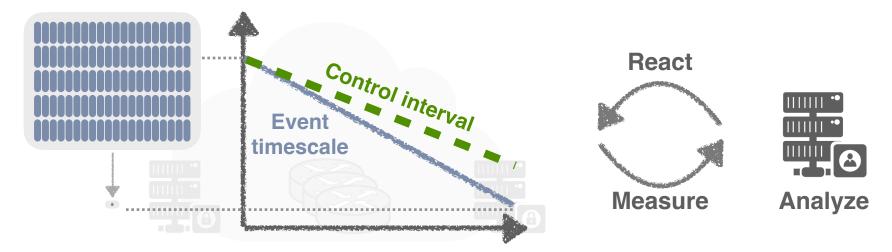


If the control interval remains coarse-grained...



If the control interval remains coarse-grained...

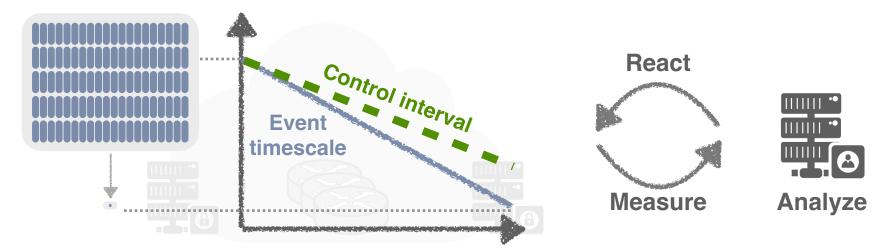
Hard to react to microscopic events



If the control interval remains coarse-grained...



If were to catch up with the link speeds...

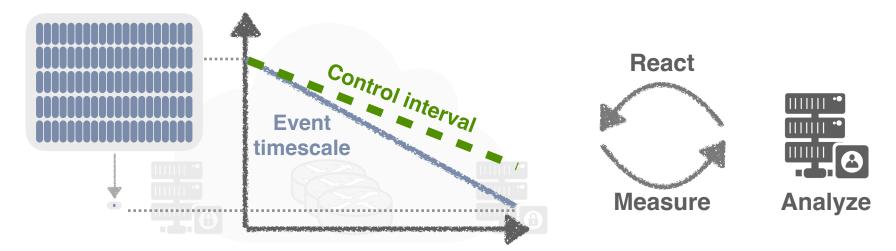


lf the control interval remains coarse-grained...

Hard to react to microscopic events

If were to catch up with the link speeds...

Allocate more cables, CPUs...?



lf the control interval remains coarse-grained...

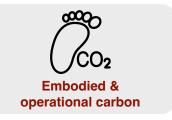
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Allocate more cables, CPUs...?

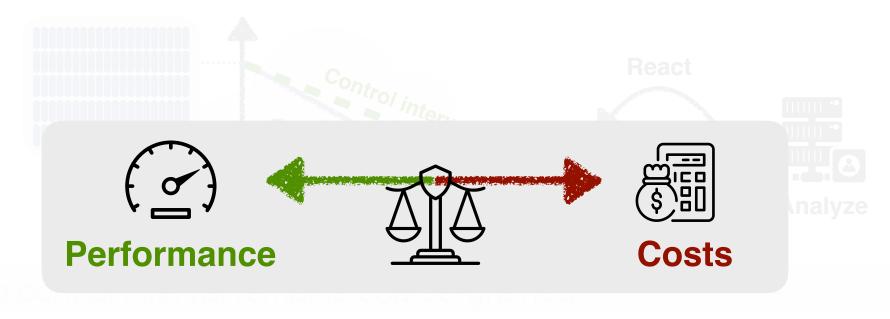












(>) Hard to react to microscopic events

If were to catch up with the link speeds...

Allocate more resources (cables, CPUs...)?

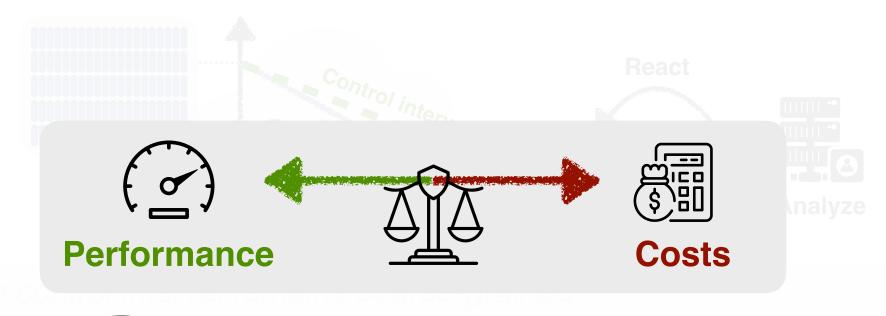


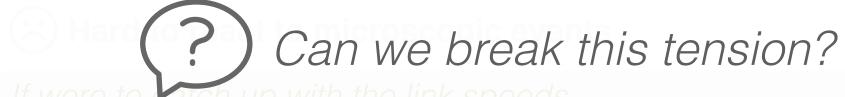












Allocate more resources (cables, CPUs...)?



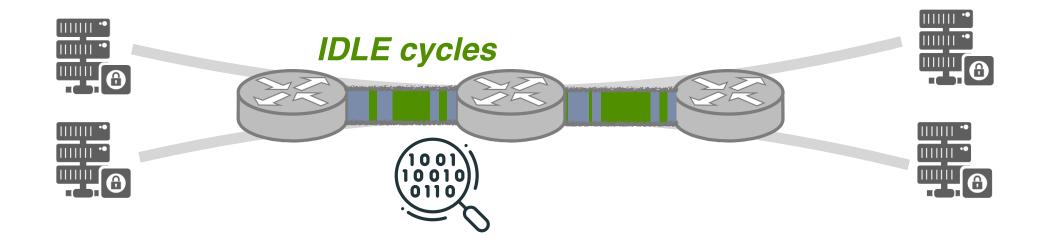




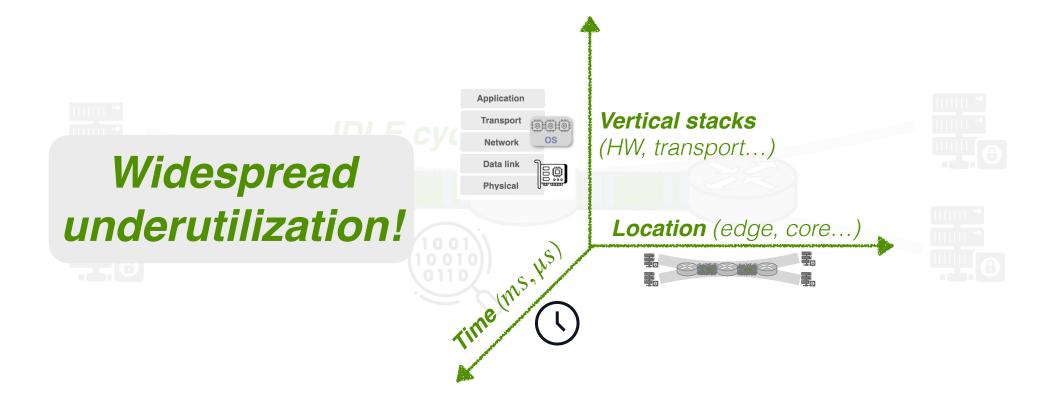




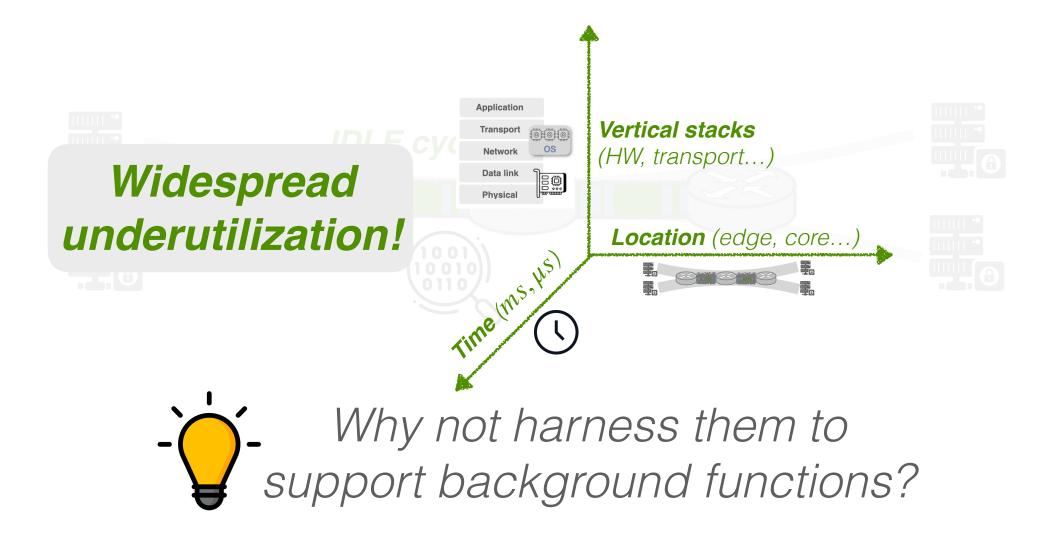
Observation: in-network waste



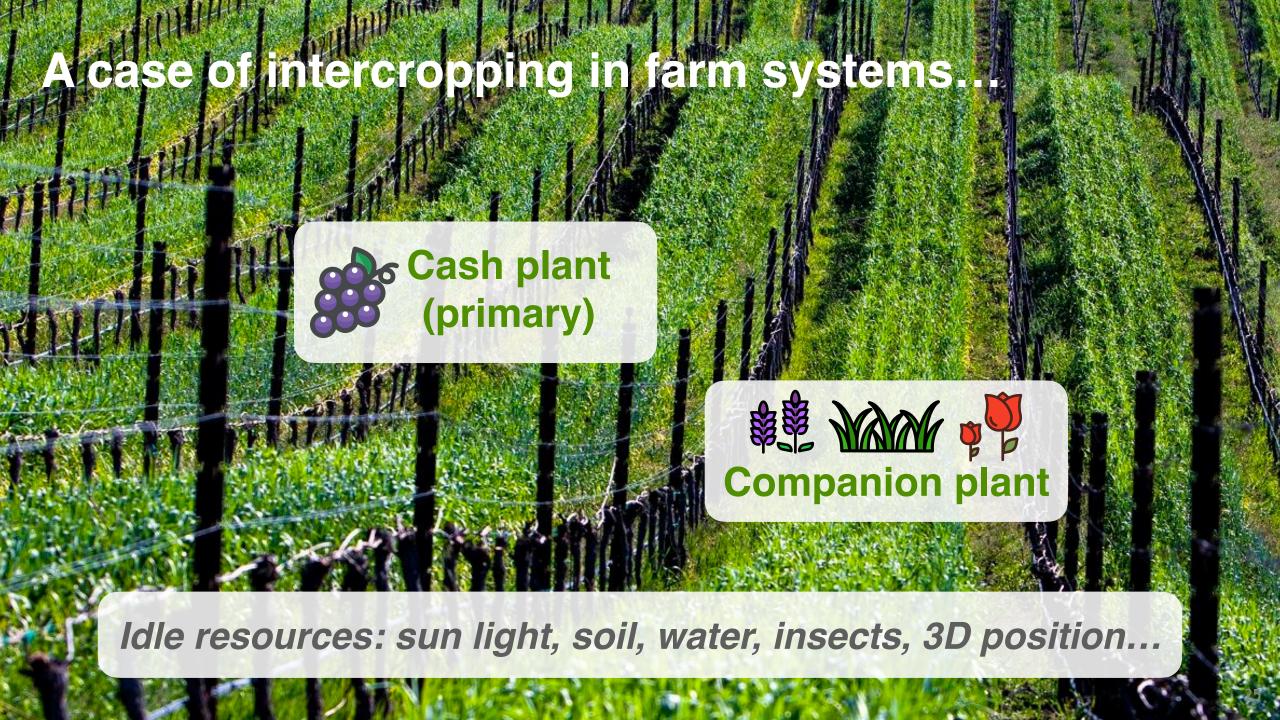
Observation: in-network waste



Observation: in-network waste







This talk: a zero-waste design approach

High-efficiency designs



Input: user workload

Goal: output a network that optimizes endto-end performance metrics with minimal resource usage

Zero-waste designs



Input: the workload and the network

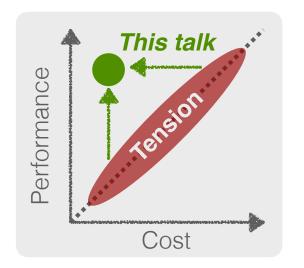
Goal: maximize the utility of **that network**, such as through uncovering the potential of the widespread in-network waste

This talk: takeaway

In-network waste is **widespread**, and in **numerous forms**

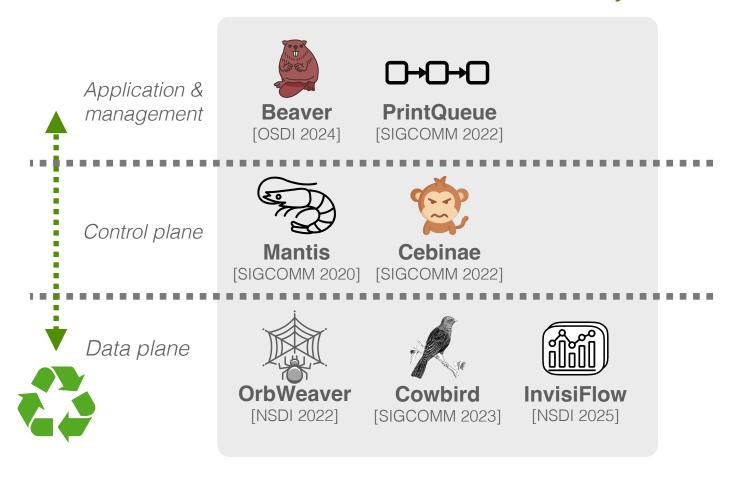
Switch CPUs
Wasted power
Memory
Spare PCIe payload
Middleboxes

By exploiting domain-specific underutilization, it is *possible* to integrate performant functions with *near-zero costs*



Research overview

Rethink the co-design of applications, software, and hardware to minimize waste in networked systems



Instantiations of zero-waste designs



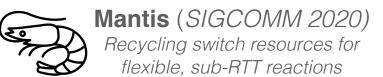
Reuse





Beaver (OSDI 2024)
Reducing 'tax' of partial snapshots for distributed cloud services

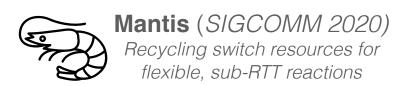
Reduce



Recycle

Outline





Recycle





Beaver (OSDI 2024)
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Reduce

• A primary goal of computer networks: *delivery packets*

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 - *User application*: video streaming, web browsing, file transfer...

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 - *Non-user application*: control messages, probes about network state, keep alive heartbeats...

- A primary goal of computer networks: delivery packets
 - *User application*: video streaming, web browsing, file transfer...
 - Non-user application: control messages, probes about network state, keep alive heartbeats...

Often, two classes of traffic multiplex the same network

When introducing a distributed coordination function...



To cost **extra bandwidth** for **efficacy**, or not?

Time synchronization

Failure detector

Congestion notification

In-band telemetry

When introducing a distributed coordination function...



To cost *extra bandwidth* for *efficacy*, or not?

Time synchronization

Failure detector

Congestion notification

In-band telemetry

clock-sync rate ↔ **clock precision**

When introducing a distributed coordination function...



To cost **extra bandwidth** for **efficacy**, or not?

Time synchronization
Failure detector
Congestion notification
In-band telemetry

clock-sync rate ↔ clock precision

keep alive message frequency ↔ detection speed

probe data/rate ↔ measurement accuracy

INT postcard volume ↔ post-mortem analysis

When introducing a distributed coordination function...

To cost **extra bandwidth** for **efficacy**, or not?

Time synchronization
Failure detector
Congestion notification
In-band telemetry

clock-sync rate ↔ clock precision

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probe data/rate ↔ measurement accuracy

INT postcard volume ↔ post-mortem analysis

Is this trade-off between overhead and fidelity necessary?

When introducing an in-band control function...

To consume extra bandwidth for efficacy, or not to?

Time synchronization clock-sync rate ↔ clock precision

Can we coordinate at *high-fidelity* with a *near-zero* cost (to usable bandwidth, latency...)?

Is this trade-off between fidelity and overhead necessary?

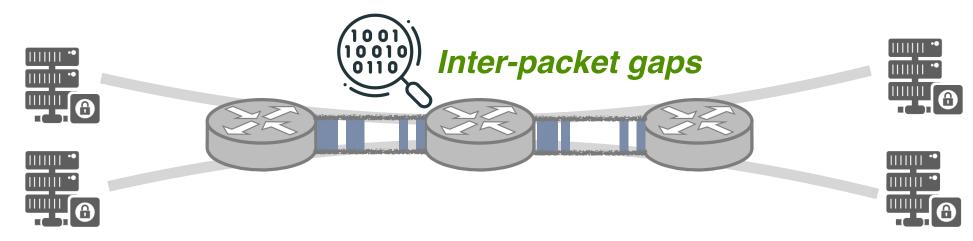
Can we coordinate at *high-fidelity* with a *near-zero* cost (to usable bandwidth, latency...)?



Idea: Weaved Stream

- Exploit $\emph{every gap}$ ($O(100 \mathrm{ns})$) between user packets opportunistically
- Inject customizable IDLE packets carrying information across devices

Opportunity: $< \mu s$ gaps are prevalent



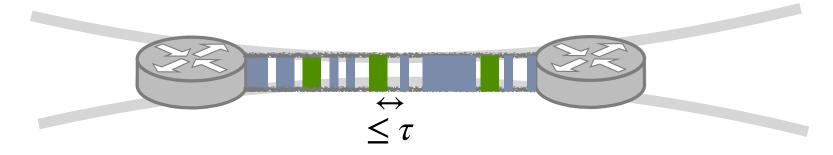
Root causes?

- Uncertainties in application load patterns (e.g., burstiness)
- Conservative resource provisioning for peak usages
- Bottlenecks at CPU processing vs network BW
- TCP effects
- Structural asymmetry
- ...

Abstraction: weaved stream



Union of user AND IDLE (injected) packets



[R1 Predictability] Interval between any two consecutive packets $\leq \tau$

$$\tau = B_{100Gbps} / MTU_{1500B} = 120ns$$

[R2 Little-to-zero overhead] Not impact user packets or power draw

Abstraction: weaved stream

Union of user and IDLE (injected) packets

Implement many in-network applications (failure detection, clock sync, congestion notification...)

for free!

[R1

$$\tau = B_{100Gbps} / MTU_{1500B} = 120ns$$

[R2 Little-to-zero overhead] Not impact user packets or power draw

Abstraction: weaved stream

Union of user and IDLE (injected) packets

Crazy idea?

Extending IDLE characters to higher layers

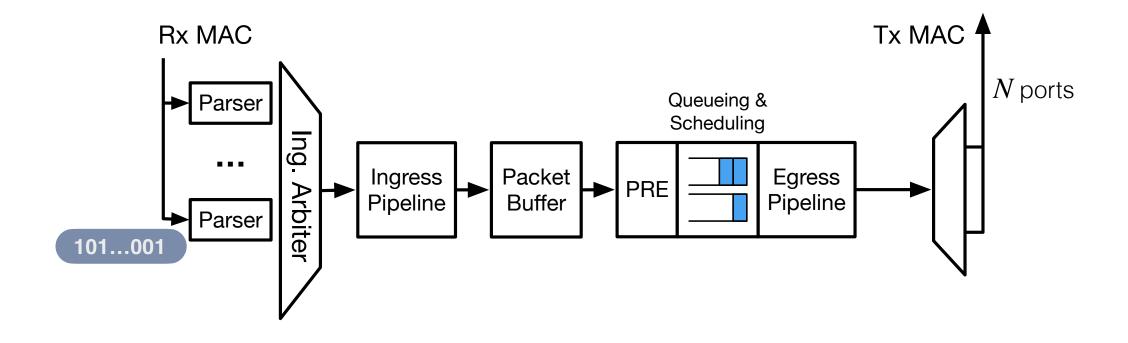
- Data plane packet generator
- Replication engine
- Data plane programmability
- Flexible switch configuration (priorities, buffers...)

[R2 Little-to-zero overhead] Not impact user packets or power draw

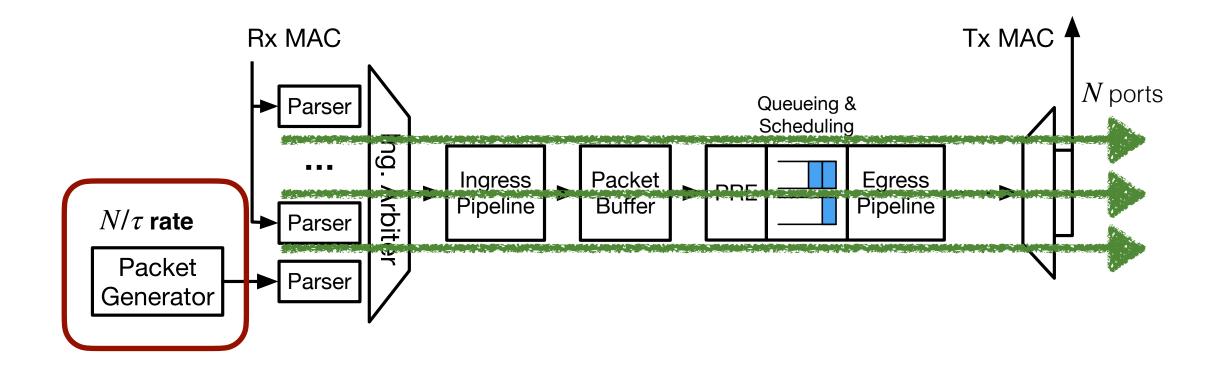
OrbWeaver: outline

- 1. Switch data plane architecture
- 2. Implementing weaved stream abstraction
- 3. OrbWeaver applications

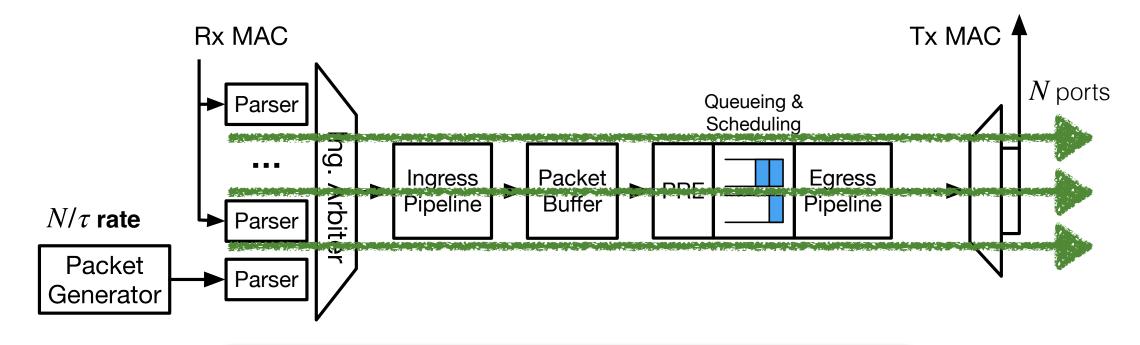
RMT switch architecture



Strawman: blind packet generation



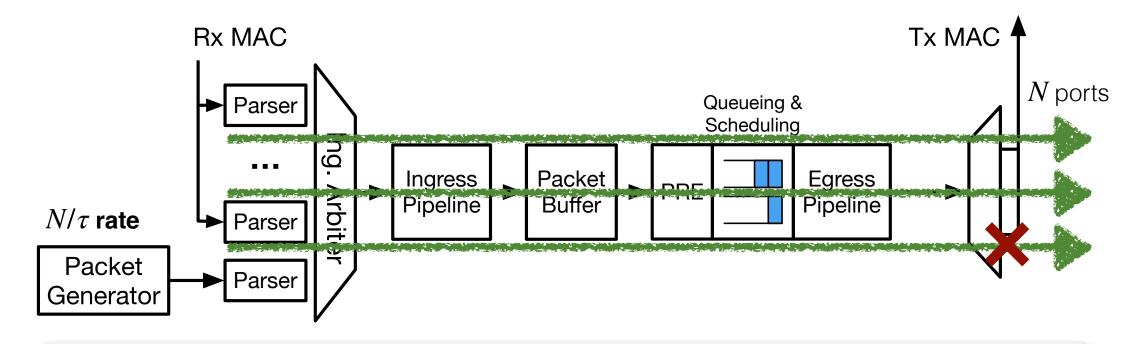
Strawman: blind packet generation



Predictability even there is no user traffic

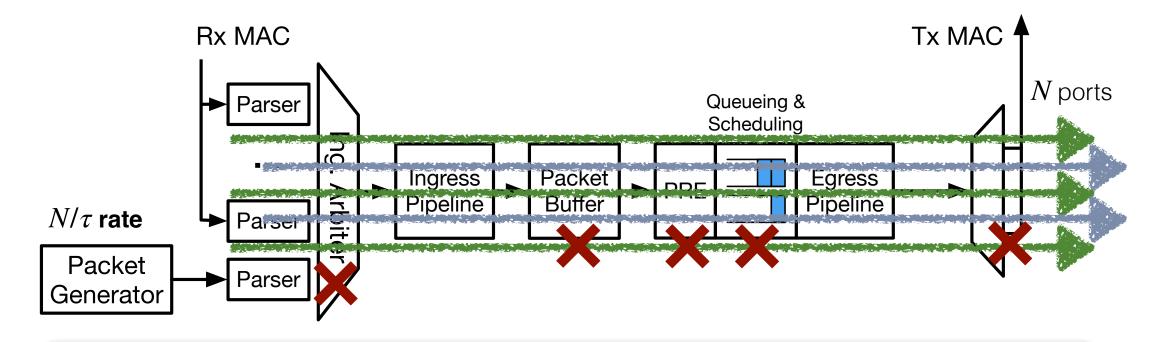


Problems with blind packet generation



#1 Scalability: overwhelm generator capacity to satisfy target rate for all ports

Problems with blind packet generation

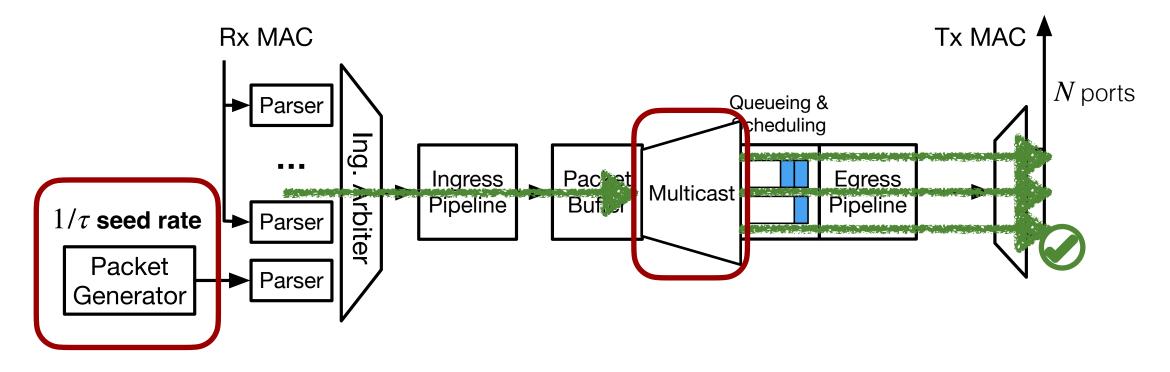


#1 Scalability: overwhelm generator capacity to satisfy target rate for all ports

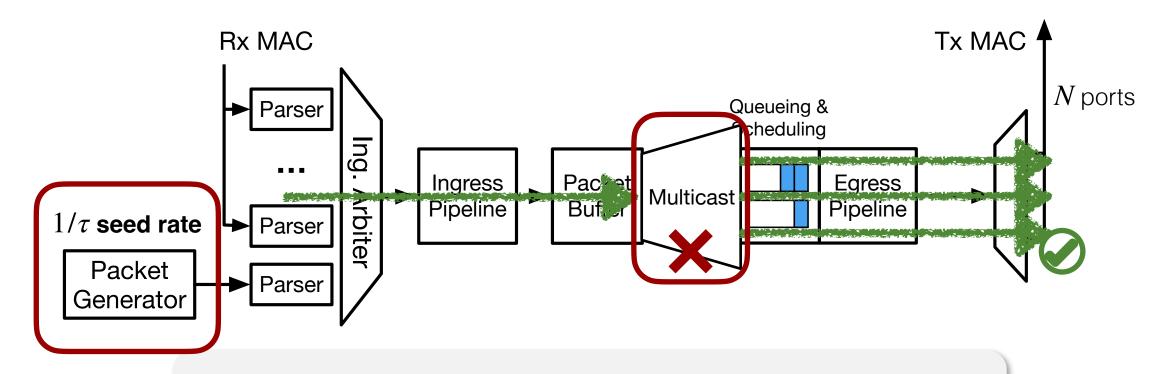
#2 Cross-traffic contention: affect throughput, latency, or loss of **user traffic!**

Problem #1: scalability

Solution: seed stream amplification



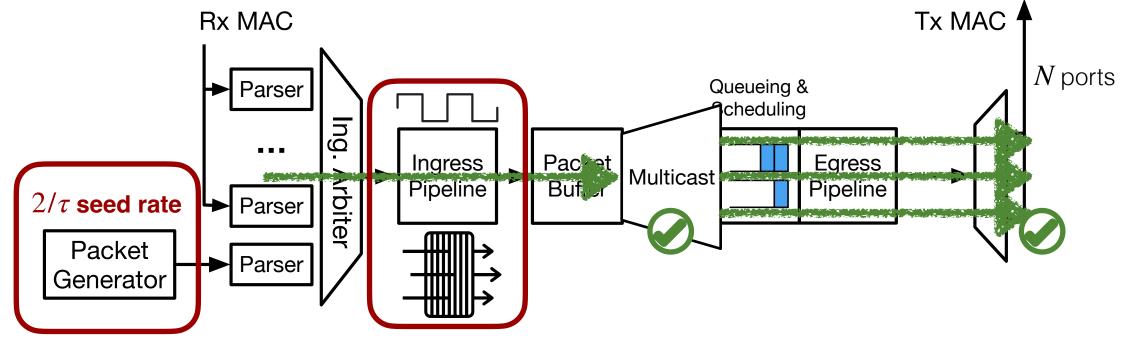
Problem #2: cross-traffic contention at PRE



Monopolize usage and waste PRE packet-level BW!

Problem #2: cross-traffic contention at PRE

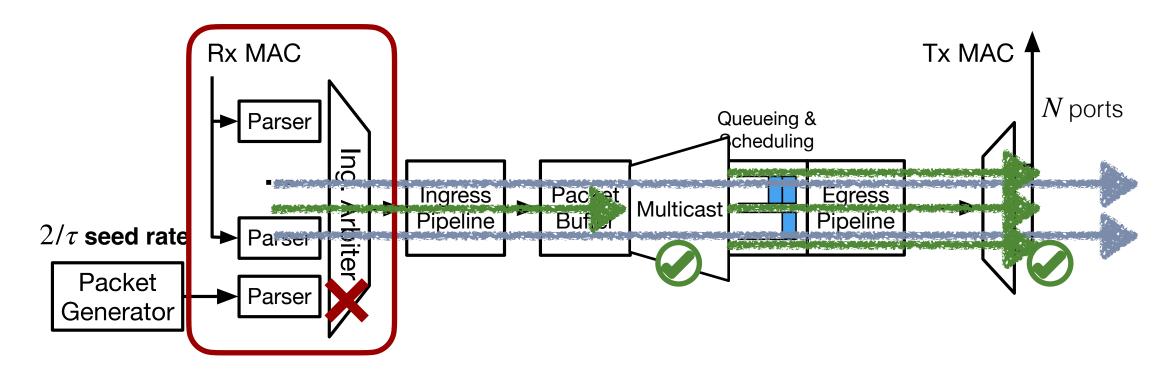
Solution: amplify seed stream on-demand



Selective filtering

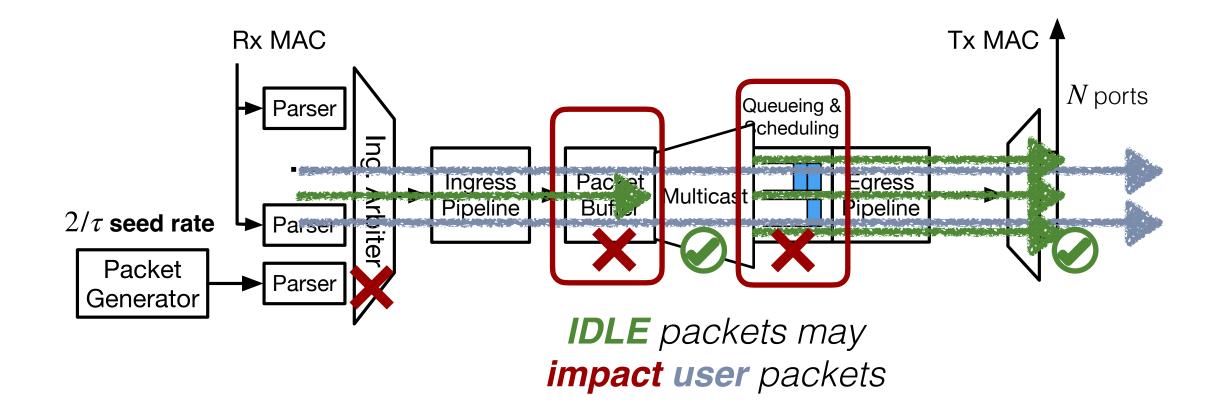
- Per-egress port bitmap indicating packet presence in the last $\tau/2$ cycle
- If not, replicate an IDLE to the port

Problem: other contention points



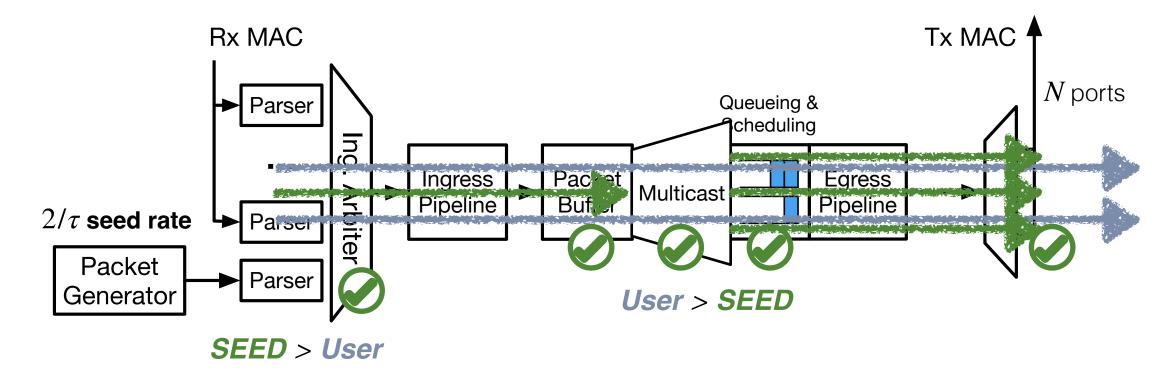
User packets may starve SEED packets

Problem: other contention points



Problem: other contention points

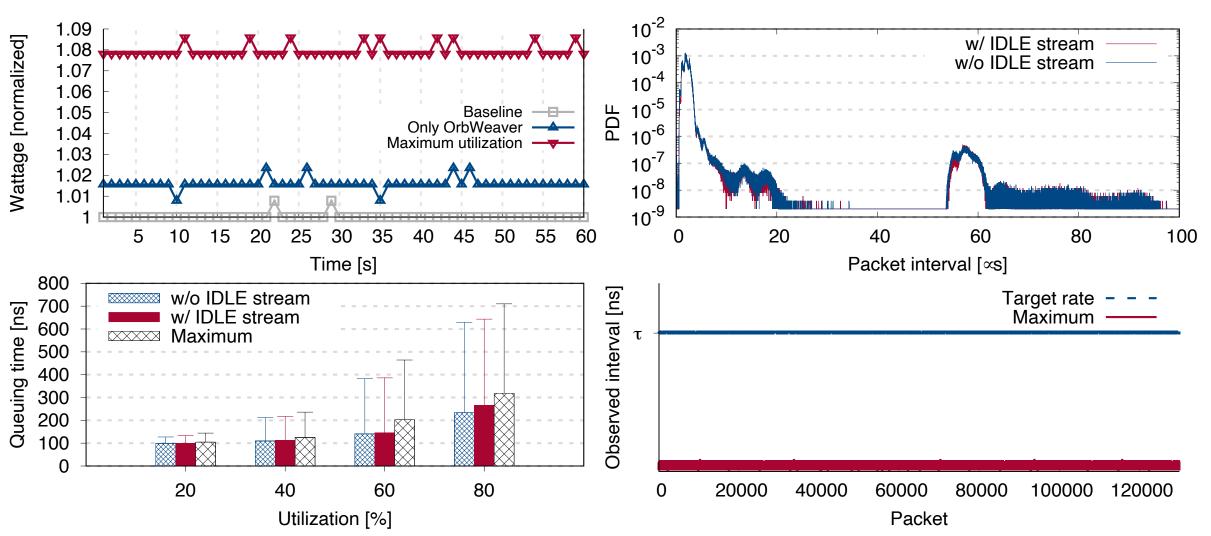
Solution: leverage rich configuration options for priorities and buffer management



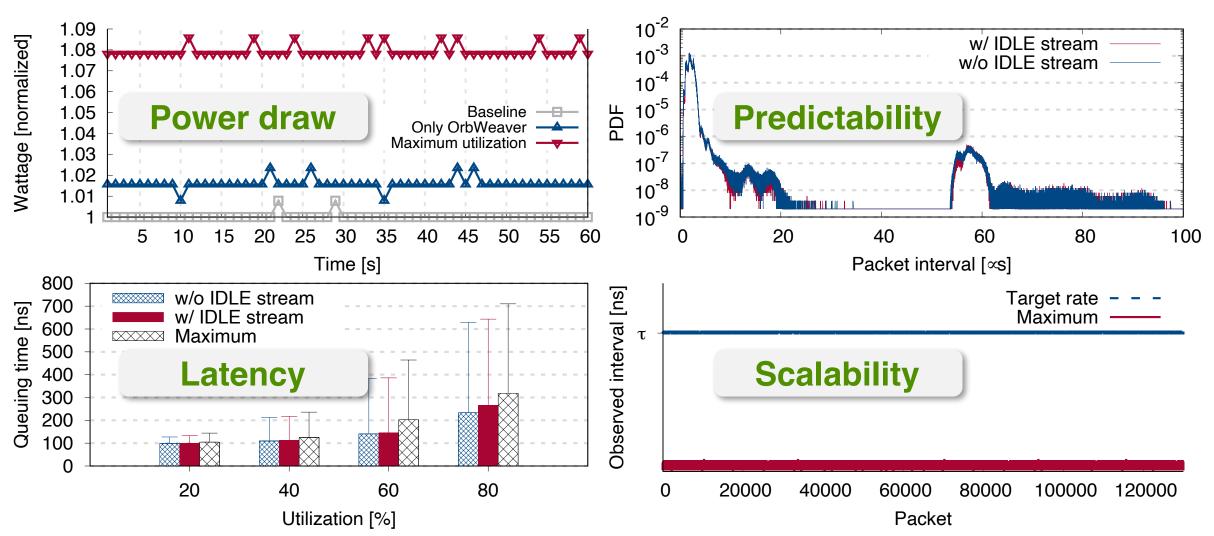
- Zero impact of weaved stream predictability
- Zero impact of user traffic throughput or buffer usage
- Negligible impact of latency of user packets

Implementation and evaluation

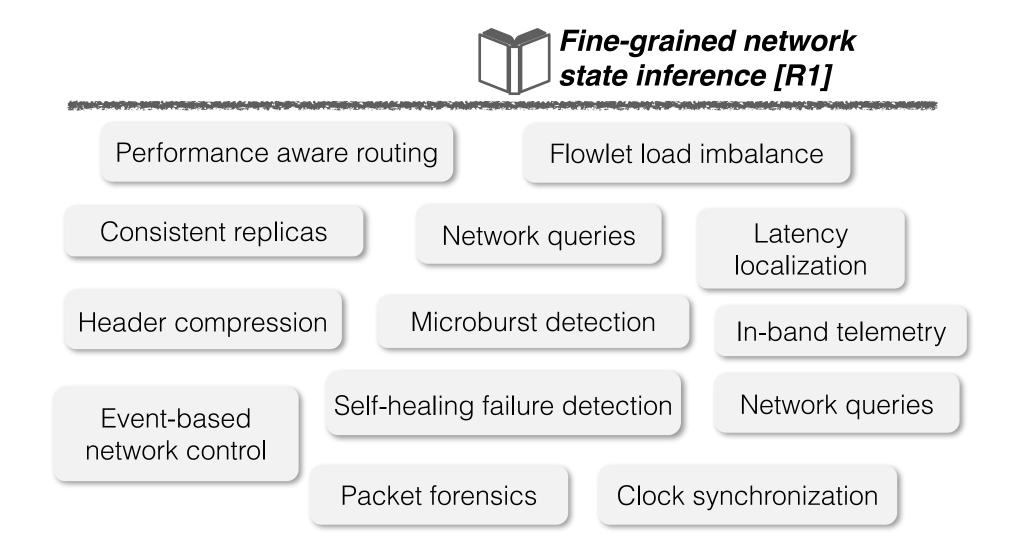
Hardware prototype on a pair of Wedge100BF-32X Tofino switches

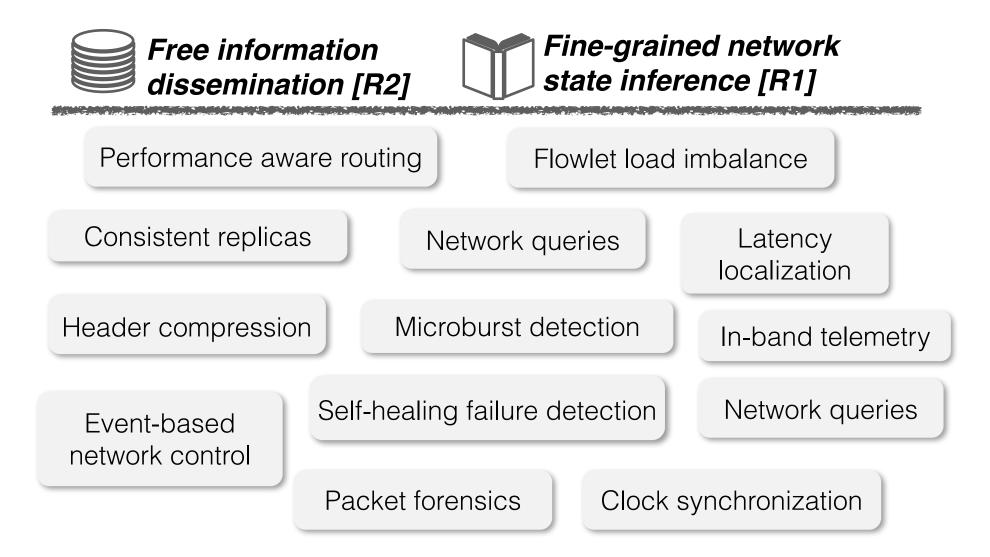


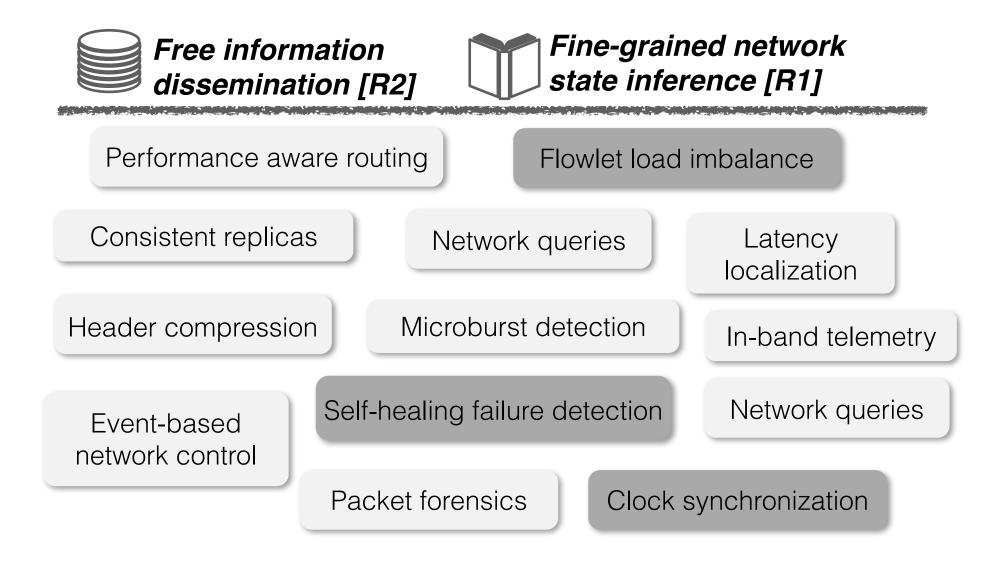
Takeaway: Little-to-no impact of power draw, latency, or throughput while guaranteeing predictability of the weaved stream!



Performance aware routing Flowlet load imbalance Consistent replicas Latency Network queries localization Header compression Microburst detection In-band telemetry Network queries Self-healing failure detection **Event-based** network control Clock synchronization Packet forensics





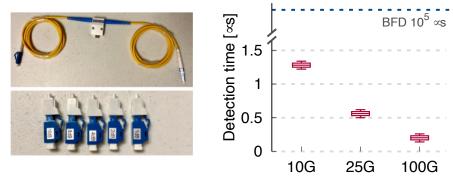


Failure detection with OrbWeaver

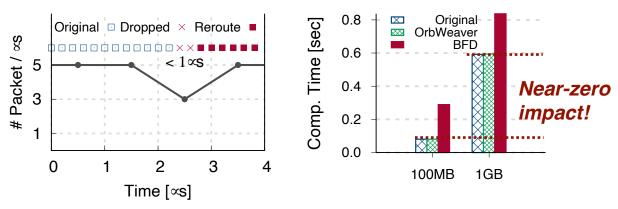


Before: Weak guarantee of the messaging channel

<u>After</u>: OrbWeaver's weaved stream abstraction guarantees maximum inter-packet gap (120ns for 100 GbE)

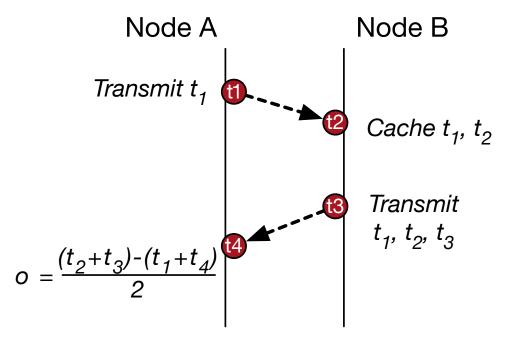


Emulated failures with optical attenuators tested under varying link speeds

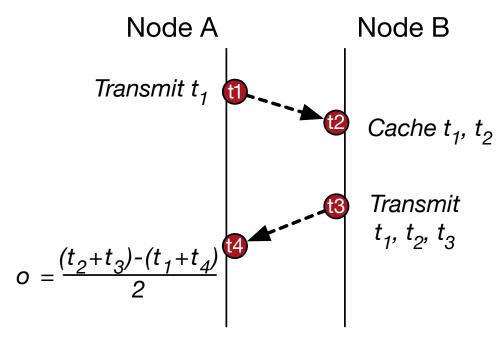


Combining it with data-plane reroute

Push the detection speed to its *limits* toward instantaneous, self-healing failure mitigation



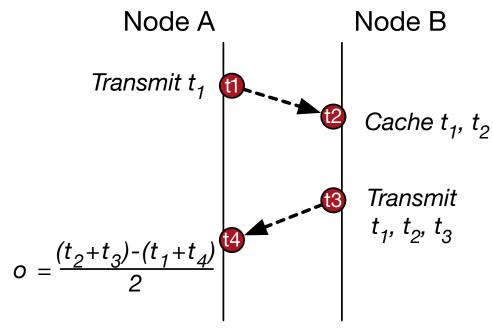
Traditional two-way protocol



Traditional two-way protocol

Existing approaches for high precision

- Require special hardware (such as DTP)
- Require messaging overheads (such as DPTP)



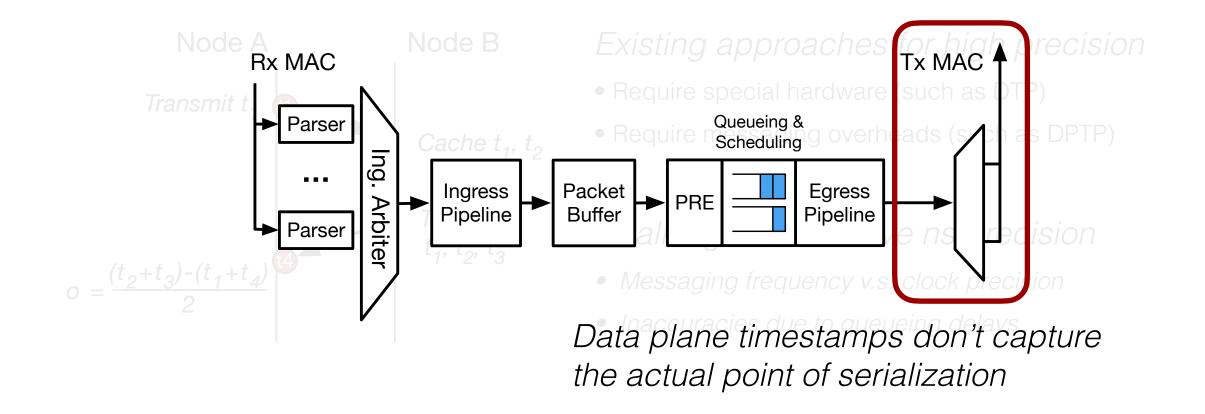
Traditional two-way protocol

Existing approaches for high precision

- Require special hardware (such as DTP)
- Require messaging overheads (such as DPTP)

Challenges to achieve ns precision

- Messaging frequency v.s. clock precision
- Inaccuracies due to queueing delays



OrbWeaver redesign

Key ideas:

1. Embed timestamp information in free IDLE packets [R2]



Key ideas:

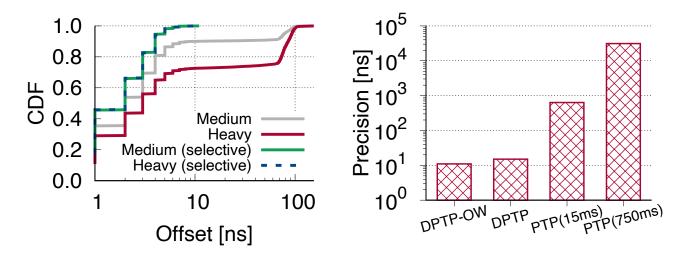
- 1. Embed timestamp information in free IDLE packets [R2]
- 2. Selective synchronization: **infer queue delay** from IDLE gaps and filter out **unreliable messages** [R1]

OrbWeaver redesign



Key ideas:

- 1. Embed timestamp information in free IDLE packets [R2]
- 2. Selective synchronization: **infer queue delay** from IDLE gaps and filter out **unreliable messages** [R1]



Achieve same or better performance with close-to-zero overheads

OrbWeaver: summary



- Weaved stream abstraction to harvest IDLE cycles
 - Push the utilization of IDLE cycles to its *limits*
 - Guarantee predictability with little-to-zero overhead

OrbWeaver: summary



- Weaved stream abstraction to harvest IDLE cycles
 - Push the utilization of IDLE cycles to its limits
 - Guarantee predictability with little-to-zero overhead
- Generic support of a wide range of data plane applications for free
 - Don't need to choose between coordination fidelity and bandwidth overhead
 - Broader implications: rethink the design of distributed coordination protocols

Outline



Reuse





Beaver (OSDI 2024)
Reducing 'tax' of partial snapshots for distributed cloud services

Reduce

Mantis (SIGCOMM 2020) Recycling switch resources for flexible, sub-RTT reactions

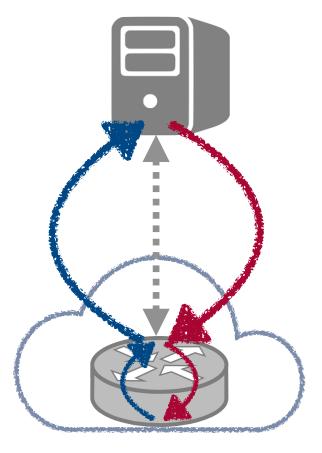
Recycle

Today's networks react

- A common task: reacting to current network conditions
 - Detecting failures and then rerouting
 - Identifying malicious flows and then filtering
 - Recognizing load imbalance and then adjusting

• In data centers, reactions need be fast

Today's primitives for reaction



SDNs or conventional control loops

Flexible but slow

Built-in data plane primitives

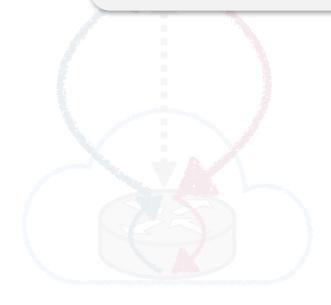
Fast but restrictive

Programmable switches?

Constraints on operations in actions, number of stages, SRAM accesses, egress/ingress communication, in-band match-action updates...

Today's primitives for reaction

Can we enable fine-grained reactions with minimum *latency* and maximum *flexibility*?



Built-in data plane primitives

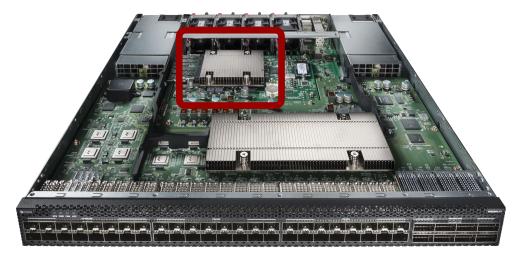
Programmable switches?

Constraints on operations in actions, number of stages, SRAM accesses, egress/ingress communication, in-band match-action updates...

A peek inside a switch chassis…

On-board CPU

ONIE, Debian/ONL, SONIC



- More capable with higher BW switching ASICs
 - Physical cores: 2→4→8
- Underlying workloads involve out-of-band, infrequent executions, e.g., IS-IS, BGP, RSVP, DHCP, LLDP, SNMP

Not part of the general compute pool, *underutilized*!

Approach

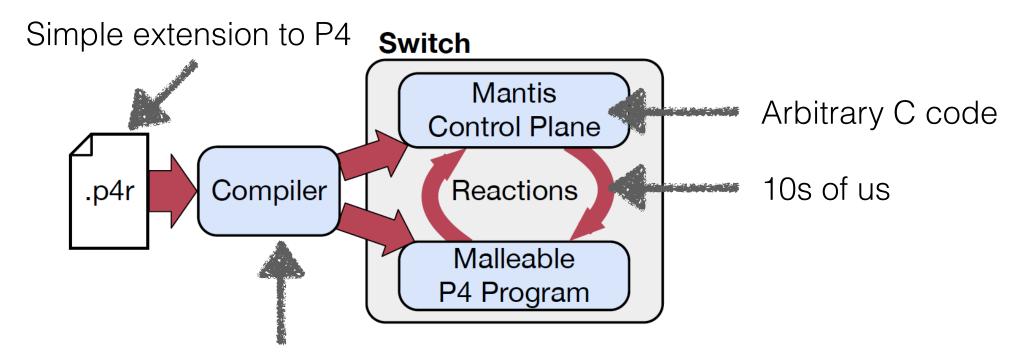
Can we enable fine-grained reactions with minimum *latency* and maximum *flexibility*?

1. Push the reactions as close to the switch ASIC as possible

2. Co-design the data plane program with local CPUs for fine-grained malleability and ease of use

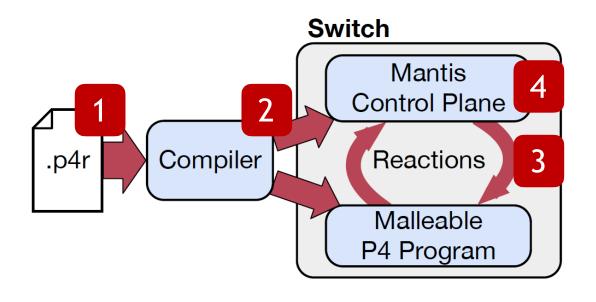
Mantis overview

Usable, fast, and expressive in-network reactions on today's RMT switches



Generates code for 'runtime' reconfigurability/serializability

Anatomy of Mantis



M1 Language

M2 Translation

M3 Isolation

M4 Execution

Abstraction

1. Malleable entities

Amenable to fine-grained reconfiguration at runtime

2. Reactions

Package reaction logic into a C-like function

M1: start with P4 code

foo.p4

```
table my_table {
  reads { ipv4.dst : ternary; }
  actions { my_action; drop; }
}
action my_action() {
  modify_field(priority, 1);
}
```

How to make it run time reconfigurable?

foo.p4r

```
table my_table {
  reads { ipv4.dst : ternary; }
  actions { my_action; drop; }
}
action my_action() {
  modify_field(priority, 1);
}
```

<u>foo.p4</u>r

```
malleable value prio_var {
  width : 16; init : 1;
}

table my_table {
  reads { ipv4.dst : ternary; }
  actions { my_action; drop; }
}
action my_action() {
  modify_field(priority, ${prio_var});
}
```

Declaring malleable entities

Previous P4 code with references to malleable entities

<u>foo.p4</u>r

```
malleable value prio var {
  width : 16; init : 1;
table my table {
  reads { ipv4.dst : ternary; }
  actions { my action; drop; }
action my action() {
  modify field(priority, ${prio var});
reaction my reaction(reg re qdepths[1:10]){
  uint16 t cur max = 0;
  for (int i = 1; i \le 10; ++i)
    if (re qdepths[i] > cur max) {
      cur max = re qdepths[i];
  if (cur max > THRESHOLD) {
   \{prio var\} = 5;
```

Declaring malleable entities

Previous P4 code with references to malleable entities

Specifying reaction arguments

Reaction with arbitrary C

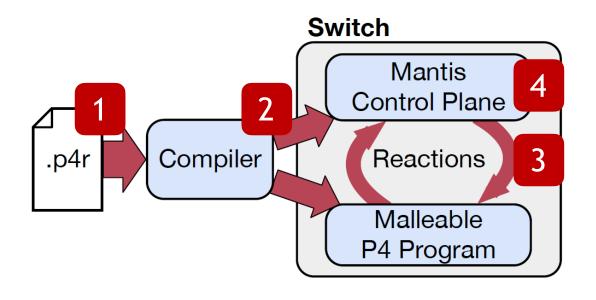
Reconfiguration

```
Malleable entities
                 Malleable value
                 Malleable field (table match, action...)

    Malleable table

              Reaction function arguments
                 Register
                 Field
                 Malleable field
cur max = re qdepths[i];
```

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M3 Isolation

M4 Execution

<u>foo.p4r</u>

```
malleable value prio var {
  width : 16; init : 1;
table my table {
  reads { ipv4.dst : ternary; }
  actions { my action; drop; }
action my action() {
  modify field(priority, ${prio_var});
reaction my_reaction(reg re_qdepths[1:10]) {
  uint16 t cur max = 0;
  for (int i = 1; i <= 10; ++i)
    if (re qdepths[i] > cur max) {
      cur max = re qdepths[i];
  if (cur max > THRESHOLD) {
    form {prio var} = 5;
```

Preparing registers for a *pull-based model*

foo.p4r

```
malleable value prio_var {
  width : 16; init : 1;
}
table my_table {
  reads { ipv4.dst : ternary; }
  actions { my_action; drop; }
}
action my_action() {
  modify_field(priority, ${prio_var});
}
```

Generalize user-specified knobs for "hitless" reconfiguration

<u>foo.p4r</u>

```
malleable value prio_var {
    width : 16; init : 1;
}
table my_table {
    reads { ipv4.dst : ternary; }
    actions { my_action; drop; }
}
action my_action() {
    modify_field(priority, ${prio_var}p4r_meta_.prio_var);
}
header_type p4r_meta_t_ {
    field {prio_var : 16;}
}
metadata p4r_meta_t_ p4r_meta_;
```

Replacing the malleable value

<u>foo.p4r</u>

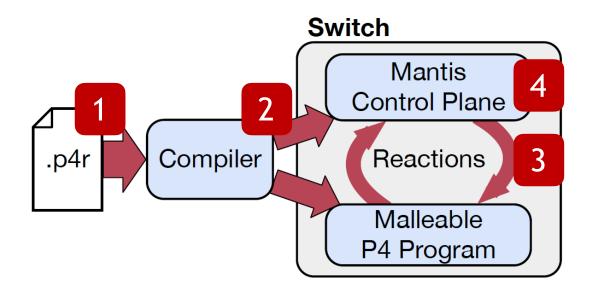
```
malleable value prio_var {
    width : 16; init : 1;
}
table my_table {
    reads { ipv4.dst : ternary; }
    actions { my_action; drop; }
}
action my_action() {
    modify_field(priority, ${prio_var}p4r_meta_.prio_var);
}
header_type p4r_meta_t_ {
    field {prio_var : 16;}
}
metadata p4r_meta_t_ p4r_meta_;
```

```
table p4r_init_ {
   actions {p4r_init_action_;}
   size : 1;
}
action p4r_init_action_(prio_var) {
   modify_field(p4r_meta_.prio_var, prio_var);
}
```

Replacing the malleable value

Multi-purpose initialization table

Anatomy of Mantis



M1 Language

M2 Translation

M3 Isolation

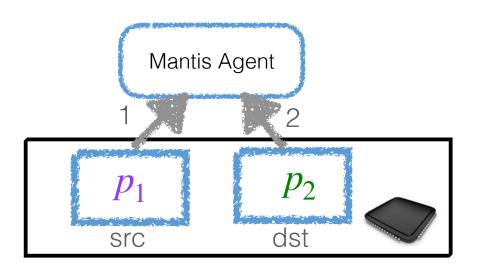
M4 Execution

M3: Isolation (ACID)

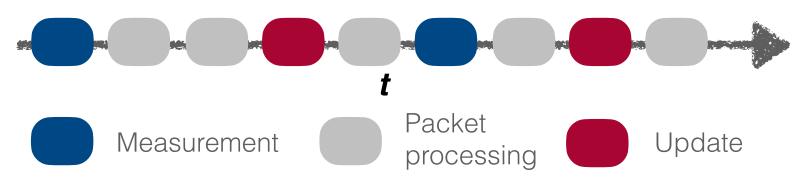
Isolation *matters*, consider

reaction my reaction(reg src, reg dst){}

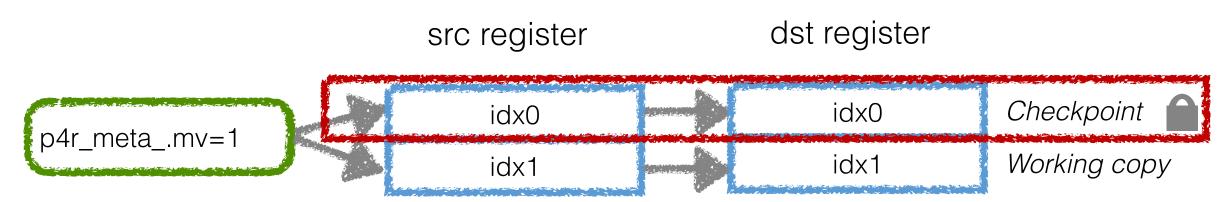
- Expectation: $src \leftarrow p_1, dst \leftarrow p_1$
- Without isolation: $src \leftarrow p_1, dst \leftarrow p_2$



Mantis enforces per-pipeline, per-reaction serializable isolation



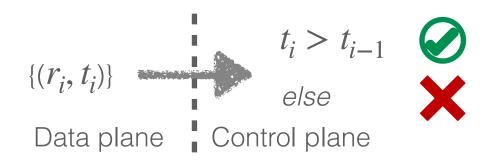
M3: Isolating measurement



Storing field arguments values

For a register, *at most* one element will be updated on a packet thread *Stale values* may appear in the current checkpoint for register arguments

Timestamps t_i appended to the duplicate buffer



M3: Isolating updates

Three-phase updates for isolating fast, repeated, partial updates

vv=0 (exact match)

Match	Action	
hdr.a=0, vv=0	my_action(0)	
hdr.a=0, vv=1	my_action(0)	
hdr.a=1, vv=0	my_action(1)	
hdr.a=1, vv=1	my_action(1)	

From previous mirror phase

 $\vee\vee=0$

Match	Action		
hdr.a=0, vv=0	my_action(0)		
hdr.a=0, vv=1	my_action(0)		
hdr.a=1, vv=0	my_action(1)		
hdr.a=1, vv=1	my_action(2)		

Prepare updates in vv=1 copy for malleable entities

Commit

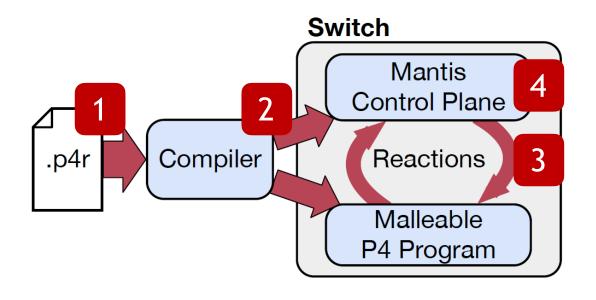
 $\vee\vee=1$

	Match	Action	
	hdr.a=0, vv=0	my_action(0)	
	hdr.a=0, vv=1	my_action(0)	
	hdr.a=1, vv=0	my_action(2)	
	hdr.a=1, vv=1	my_action(2)	

Mirror the changes to the shadow copy for amortization

Bounded memory overhead and predictable latency

Anatomy of Mantis



M1 Language

M2 Translation

M3 Isolation

M4 Execution

M4: Mantis control plane

Traditionally data/control plane interactions are treated as *one-off,* isolated events, i.e., assumed to be "on the slow path"

Mantis control plane is instead *reaction-centric*

```
helper_state = precompute_metadata();
memo = setup_cache(helper_state);
run_user_initialization(helper_state, memo);

while(!stopped) {
    updateTable(memo, "p4r_init_", {measure_ver : mv ^ 1});
    read_measurements(memo, mv); mv ^= 1;
    run_user_reaction(memo, helper_state, vv ^ 1);
    updateTable(memo, "p4r_init_", {config_ver : vv ^ 1});
    fill_shadow_tables(memo, vv); vv ^= 1;
}
Dialogue
```

~PCIe latency of the underlying system

Implementation and evaluation

Prototype implementation on a Wedge100BF-32X Tofino switch

- P4R frontend: Flex/Bison based, ~5000 lines of C++ and grammar
- Mantis agent: dynamic (re)loading of user reaction (.so object)

Implementation and evaluation

Prototype implementation on a Wedge100BF-32X Tofino switch

- P4R frontend: Flex/Bison based, ~5000 lines of C++ and grammar
- Mantis agent: dynamic (re)loading of user reaction (.so object)

Evaluation

- How fast is Mantis's reaction time?
- What is the overhead?
- What are the applications of Mantis?
- How does Mantis compare to existing alternatives?

Use cases

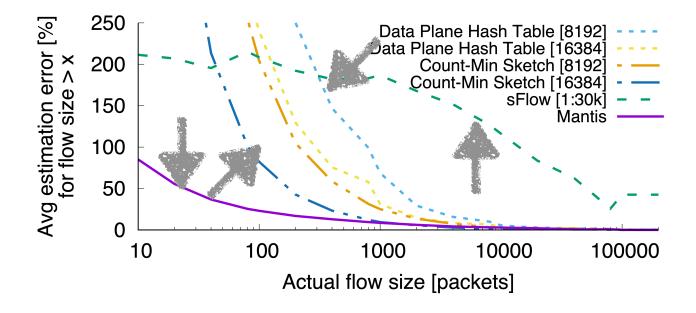
	DoS mitigation	Route Recomputation	Hash polarization mitigation	Reinforcement Learning
Measurement	Flow signature, packet count	Heartbeat counts, timestamp	Queue depths of ECMP ports	Packet counts and queue depths
Control logic	Block the sender if the estimated flow size exceeds a threshold	Mark the failed link if received heartbeat number is small than expected after consecutive K confirmations	Change ECMP hashing input to another permutation if found a persistent imbalance of port utilization	Use a Q-learning algorithm to calculate the optimal ECN threshold based on rewards
Reconfiguration	Drop the malicious traffic for the blocked senders	Reroute traffic towards the affected link	Reconfigure the malleable fields for another 5-tuple permutation	Change ECN malleable value

Flow size estimation

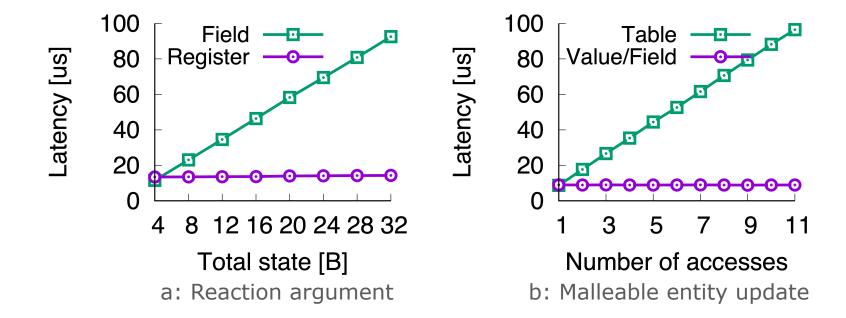
- Evaluation setting
 - CAIDA traces, 20s chunk, 10Gbps link of ISP backbone
- Arguments
 - packet source IP and packet counter
- Algorithm

• Estimation formula
$$rac{\hat{f}_t - \hat{f}_{t_0}}{t - t_0}$$

- t_0 : timestamp when first observe the flow
- Mantis sampling rate: every 10us, ~1 in 5 packets



Mantis achieves fast reaction times

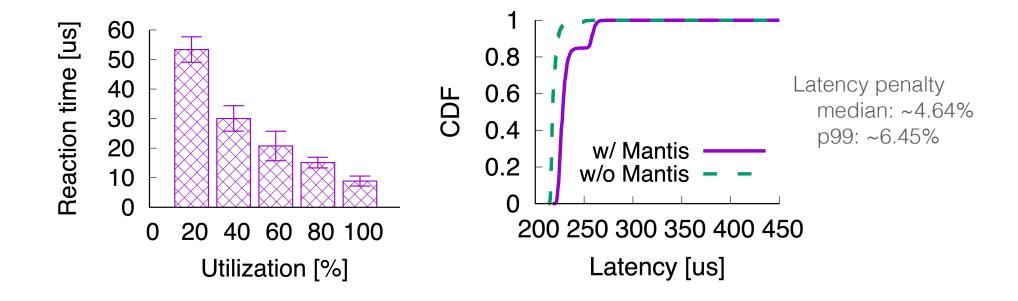


$$F_{\text{b}}(1 \text{ tblMod}) + \sum_{a \in \textit{args}} \left(F_{\text{a}}(a) \right) + C + \sum_{t \in \textit{tblMods}} \left(2F_{\text{b}}(t) \right) + 2F_{\text{b}}(N_{\textit{init}} - 1) + F_{\text{b}}(1 \text{ tblMod})$$

End-to-end reaction time: 10s of us

Mantis CPU overhead

A dialogue loop occupies up to a single core but can be throttled



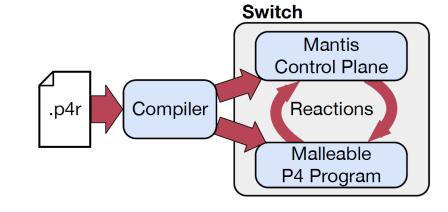
Overall, Mantis can *co-exist* with other functionalities

Summary

- Fine-grained reaction to network statistics as first class citizen
- P4R interface to simplify the encoding of serializable reaction
- Generic support of sub-RTT reactive behaviors

Mantis can be used for...

- Encoding flexible control logic
- Workarounds of current limitations
- Reducing memory overhead via offloading
- Data/control plane co-design





https://github.com/eniac/Mantis

Outline



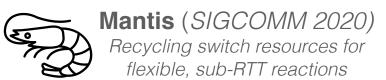
Reuse



Beaver (OSDI 2024)

Reducing 'tax' of partial snapshots for distributed cloud services

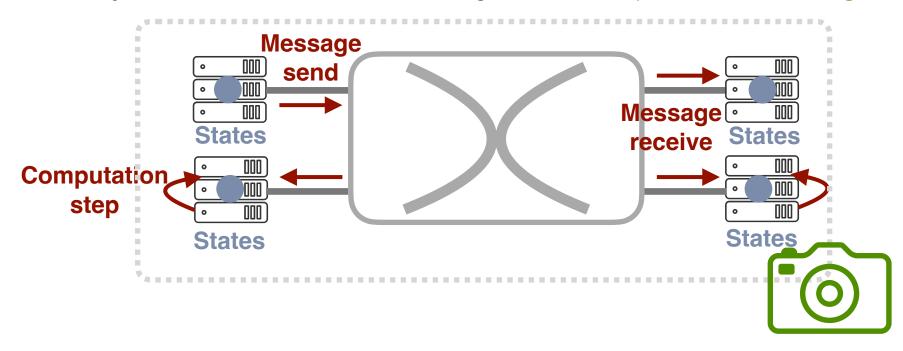
Reduce



Recycle

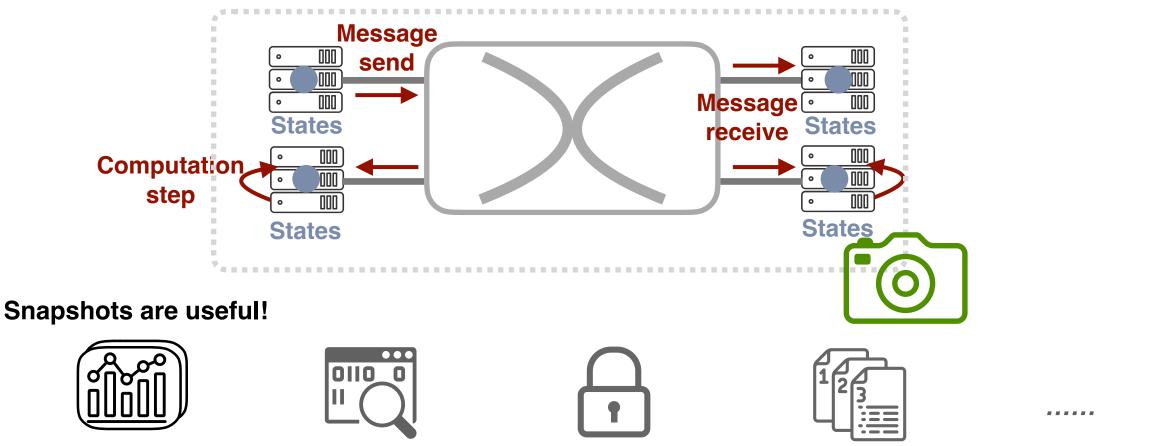
Let's talk about snapshots

Distributed snapshots: a class of distributed algorithms to capture consistent, global view of states



Let's talk about snapshots

Distributed snapshots: a class of distributed algorithms to capture consistent, global view of states



Network telemetry Distributed software Deadlock detection debugging

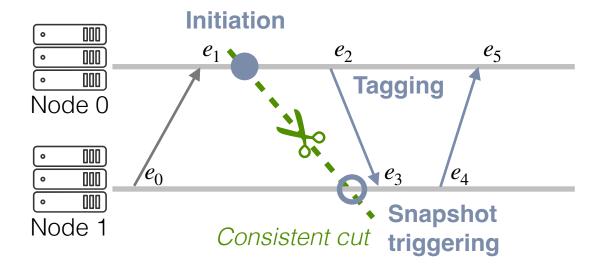
Checkpointing and failure recovery

Classic distributed snapshots

e.g., Chandy-Lamport (TOCS 1985)

Classic distributed snapshots

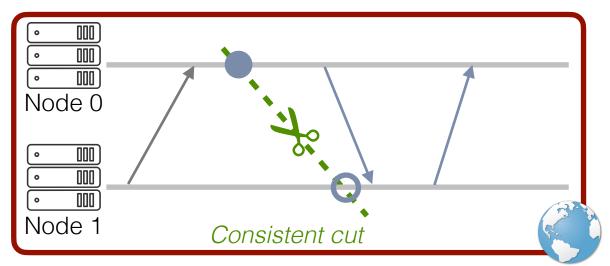
e.g., Chandy-Lamport (TOCS 1985)



Guarantee of causal consistency



Classic snapshots operate in an isolated universe



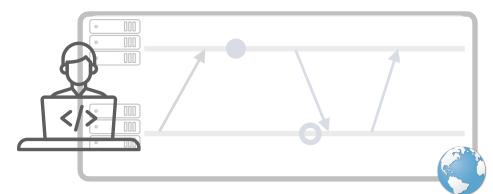
Utopian: isolated 'universe' of nodes

Fundamental assumption:

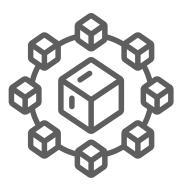
The set of participants are *closed* under causal propagation.



The assumption rarely matches reality!



Utopian: isolated 'universe' of nodes



Modular services



Instrumentation constraints



Costs and overheads



Hidden causality due to human

The assumption mismatches the reality!









Unrealistic to assume *zero* external interaction Impractical to instrument *all* processes

Utopian: isolated 'universe' of nodes

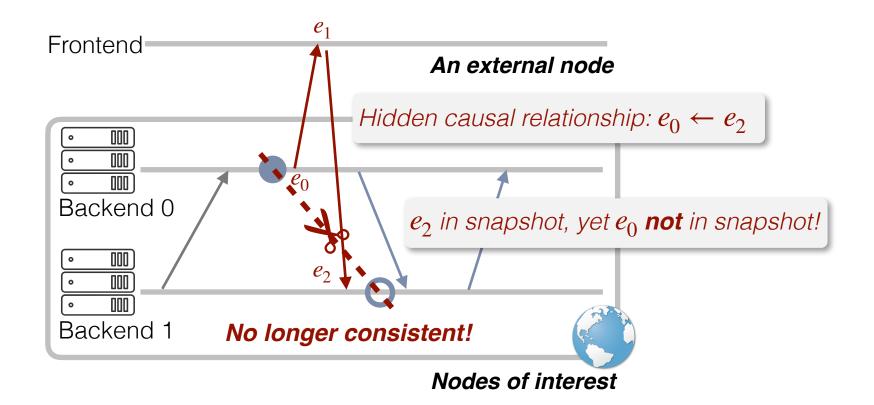




Costs and overheads

Hidden causality due to human

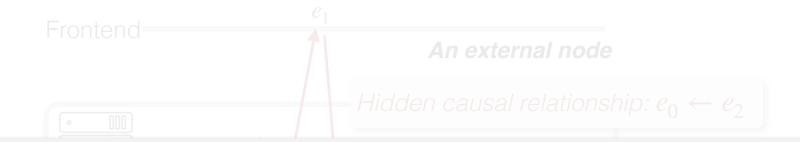
Consequences?



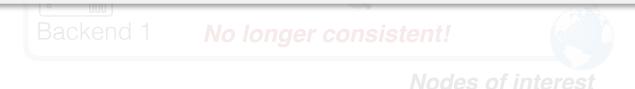


A single external node can break the guarantee!

Consequences?



Can we capture a *causally consistent* snapshot when a *subset* of the broader system participates?



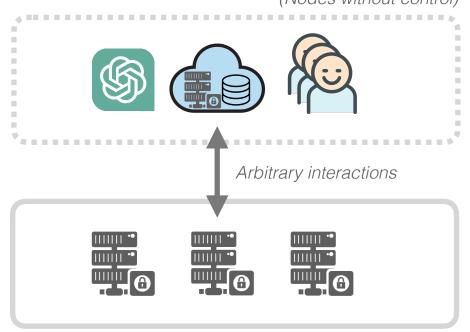


Beaver: practical partial snapshots



Out-group nodes

(Nodes without control)



In-group nodes

(Nodes with VIPs of interest)



The same causal consistency abstraction

Even when the target service interact with **external**, **black box services** (arbitrary number, scale, placement, or semantics) via **arbitrary pattern** (including multi-hop propagation of causal dependencies)

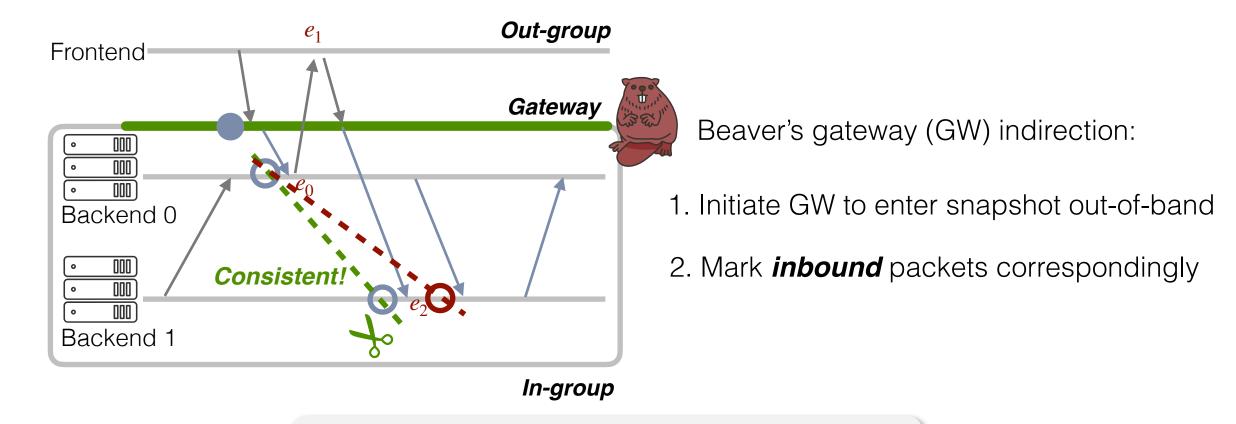


Zero impact over existing service traffic

That is, absence of blocking or any form of delaying operations during distributed coordination



Idea 1: Gateway (GW) indirection



Before: **inconsistent** cut at \mathbf{O} (after e_2)

With GW: **consistent** cut at \bigcirc (before e_2)

Formalizing idea 1: Monolithic Gateway Marking

Theorem 1. With MGM, a partial snapshot C_{part} for $P^{in} \subseteq P$ is causally consistent, that is, $\forall e \in C_{part}$, if $e' \cdot p \in P^{in} \land e' \rightarrow e$, then $e' \in C_{part}$.

Proof. Let $e.p = p_i^{in}$ and $e'.p = p_i^{in}$. There are 3 cases:

- 1. Both events occur in the same process, i.e., i = j.
- 2. $i \neq j$ and the causality relationship $e' \rightarrow e$ is imposed purely by in-group messages.
- 3. Otherwise, the causality relationship $e' \rightarrow e$ involves at least one $p \in P^{out}$.

In cases (1) and (2), the theorem is trivially true using identical logic to proofs of traditional distributed snapshot protocols. We prove (3) by contradiction.

Assume $(e \in C_{part}) \land (\exists e' \rightarrow e)$ but $(e' \notin C_{part})$. With (3), $e' \rightarrow e$ means that there must exist some e^{out} (at an out-group process) satisfying $e' \rightarrow e^{out} \rightarrow e$. Now, because $e' \notin C_{part}$, we know $e^{ss}_{p^{in}_j} \rightarrow e'$ or $e^{ss}_{p^{in}_j} = e'$, that is, p^{in}_j 's local snapshot happened before or during e'. Combined with the fact that the

gateway is the original initiator of the snapshot protocol, we know that $e_g^{ss} \to e' \to e^{out} \to e$. We can focus on a subset of the above causality chain:

 $e_g^{ss} \rightarrow e$. From the properties of the in-group snapshot protocol, $e_g^{ss} \rightarrow e$ implies that $e \notin C_{part}$.

This contradicts our original assumption that $e \in C_{part}$!

Formal proof in paper



Holds even if treating the out-group nodes as black boxes



Sufficient to *only* observe the inbound messages

Key ideas in Beaver

How to ensure consistency without coordinating external machines?

Idea 1: Indirection through Monolithic Gateway Marking (MGM)

How to enforce MGM practically in today's network?

Challenge 1 How to instantiate GW?

Challenge 2 How to handle asynchronous GWs?

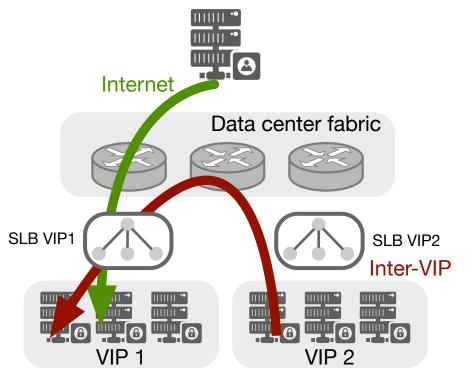
Challenge 1: instantiating GWs



Rerouting all inbound traffic through the GW is *costly*



Cloud data centers already place layer-4 load balancers (SLBs)





Key ideas in Beaver

How to ensure consistency without coordinating external machines?

Idea 1: Indirection through Monolithic Gateway Marking (MGM)

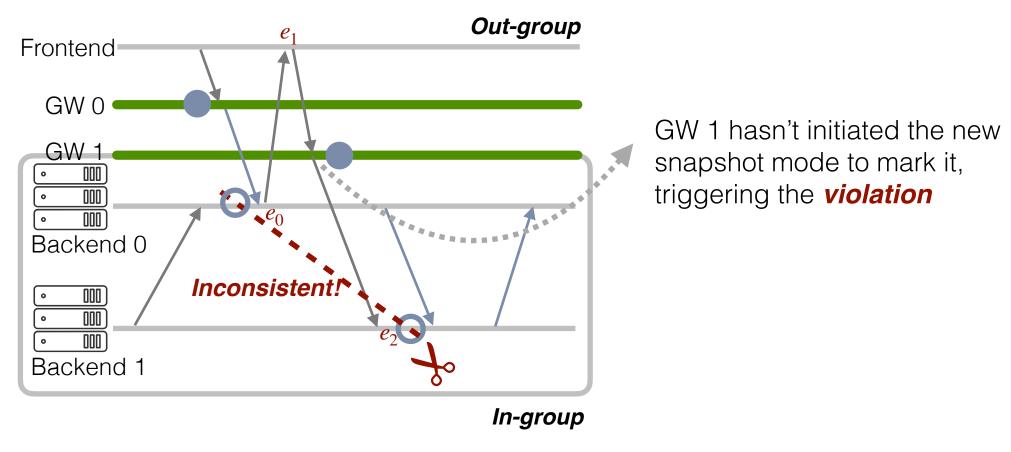
How to enforce MGM practically in today's network?

Challenge 1 How to instantiate GW?

Idea 2: Reuse existing SLBs with unique locations

Challenge 2 How to perform atomic snapshot initiation for asynchronous GWs?

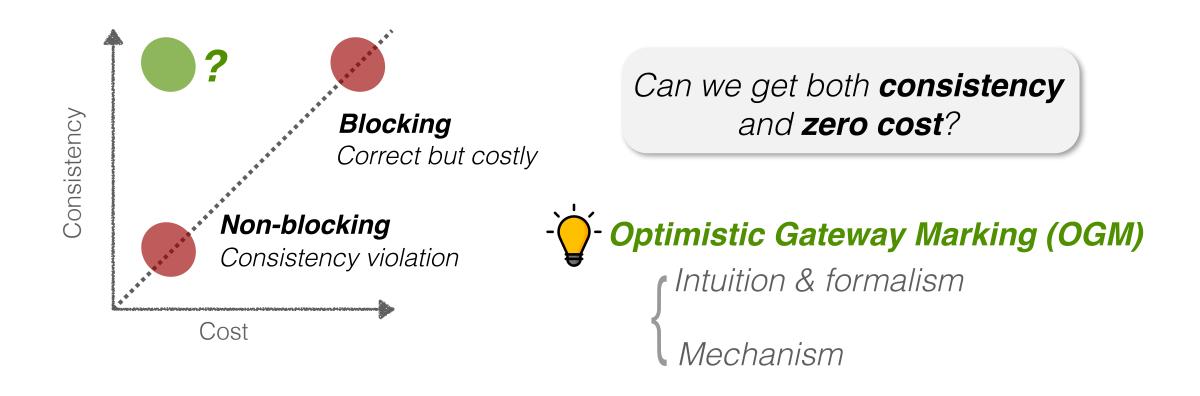
Implications of multiple SLBs



 e_2 in snapshot, yet e_0 that leads to it is not, inconsistent!

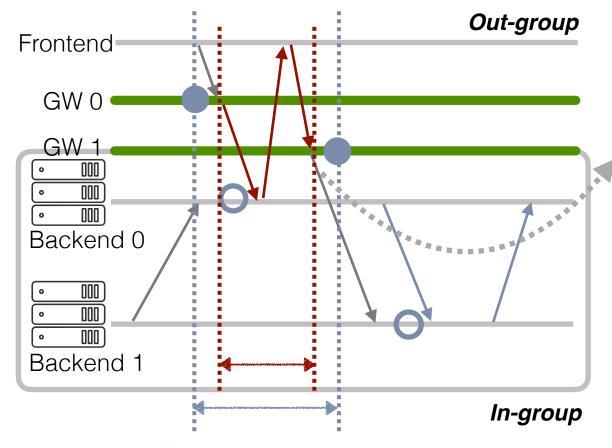
Handling multiple GWs: design space

How about blocking messages to 'atomically' trigger all SLBs?



Challenge 2: handling multiple SLBs

Reflection: Beyond worst cases, when and how often does the violation occur?



Time gap between SLB initiation points

Observation:

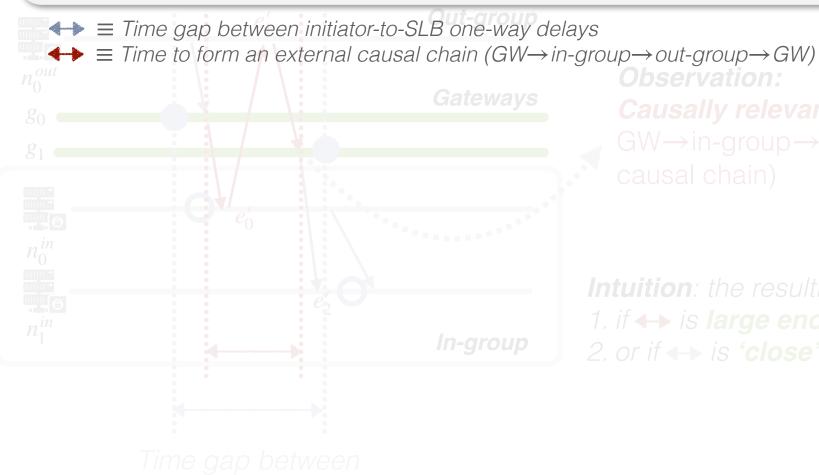
Causally relevant messages are rare! GW→in-group→out-group→GW (external causal chain)

Intuition: the resulting snapshot is consistent

1. if → is large enough

2. or if ←→ is 'close' enough

Theorem: if ↔ < ↔, the partial snapshot is consistent!



Theorem 2. In a system with multiple asynchronous gateways, let the wall-clock time of the first and last gateway snapshots be $e_{gmin}^{ss} = \min_{e_g^{ss}}(e_g^{ss}.t)$ and $e_{gmax}^{ss} = \max_{e_g^{ss}}(e_g^{ss}.t)$, respectively. Also let $\forall g \in G$, $\tau_{min} = min(d(g, g'; \{p, q\}))$, where $g, g' \in G, p \in P^{in}, and q \in P^{out}.$ If $e_{gmax}^{ss}.t - e_{gmin}^{ss}.t < \tau_{min}$ then the partial snapshot is causally consistent.

Proof. We extend the proof of Theorem 1 to a distributed setting. Similar to Theorem 1, there are three cases, with (3) being the one that differs. We again prove it by contradiction.

Assume $(e \in C_{part}) \land (\exists e' \to e)$ but $(e' \notin C_{part})$. As before, there must be some chain $e' \to e^{out} \to e^g \to e$. Because $e' \notin$ C_{part} , we have $e_{p_{in}^{in}}^{ss} \rightarrow e'$ or $e_{p_{in}^{in}}^{ss} = e'$, that is, p_{j}^{in} must have been triggered directly or indirectly by an inbound message. Denote the arrival of this inbound message at its marking gateway as $e^{g'}$. By the definition of τ_{min} , we have $e^g \cdot t - e^{g'} \cdot t \ge 1$ $\tau_{min} > e_{gmax}^{ss}.t - e_{gmin}^{ss}.t$. Thus, at event e^g , the gateway must have already initiated the snapshot and will mark e^g . m before forwarding. This results in $e \notin C_{part}$, a contradiction!

Formal proof in paper

Theorem: if ↔ < ↔, the partial snapshot is consistent!

- **→** ≡ Time gap between initiator-to-SLB one-way delays
- \Rightarrow \equiv Time to form an external causal chain (GW \rightarrow in-group \rightarrow out-group \rightarrow GW)

Observation: condition holds in most cases anyway!

- ← can approximate zero
- SLBs share the same region
- Proper placement of controller

- → is relatively high
- ≥ 3 trips through the fabric
- Higher when the out-group is in another DC or Internet

Optimistic execution in common cases

1. if \is large enough

Optimistic Gateway
Marking (OGM)

Verification/rejection of snapshots under worst cases

Theorem 2. In a system with multiple asynchronous gateways, let the wall-clock time of the first and last gateway snapshots be $e_{gmin}^{ss} = \min_{e_s^{ss}}(e_s^{ss}.t)$ and $e_{gmax}^{ss} = \max_{e_s^{ss}}(e_s^{ss}.t)$, respectively. Also let $\forall g \in G$, $\tau_{min} = \min(d(g,g';\{p,q\}))$, where $g,g' \in G$, $p \in P^{in}$, and $q \in P^{out}$. If $e_{gmax}^{ss}.t - e_{gmin}^{ss}.t < \tau_{min}$, then the partial snapshot is causally consistent.

Proof. We extend the proof of Theorem 1 to a distributed setting. Similar to Theorem 1, there are three cases, with (3) being the one that differs. We again prove it by contradiction.

Assume $(e \in C_{part}) \land (\exists e' \to e)$ but $(e' \notin C_{part})$. As before, there must be some chain $e' \to e^{out} \to e^{s} \to e$. Because $e' \notin C_{part}$, we have $e_{pj}^{ss} \to e'$ or $e_{pj}^{ss} = e'$, that is, p_j^{in} must have been triggered directly or indirectly by an inbound message. Denote the arrival of this inbound message at its marking gateway as $e^{g'}$. By the definition of τ_{min} , we have $e^g.t - e^g.t \le \tau_{min} \lor e_{gmax}^g.t - \tau_{min}^g.t$. Thus, at event $e^g.$ the gateway must have already initiated the snapshot and will mark $e^g.m$ before forwarding. This results in $e \notin C_{part}$, a contradiction!

Formal proof in paper

How does Beaver detect a snapshot violation?

Theorem: if ↔ < ↔, the partial snapshot is consistent

```
\Rightarrow \equiv Time gap between initiator-to-SLB one-way delays
\Longrightarrow Time to form an external causal chain (GW\rightarrowin-group\rightarrowout-group\rightarrowGW)
```



- Determine the lower bound of → statically
 Measure a safe upper bound for → online using a single clock



False positives is fine as one can always retry!

Key ideas in Beaver

How to ensure consistency without coordinating external machines?

Idea 1: Indirection through Monolithic Gateway Marking (MGM)

How to enforce MGM practically in today's network?

Challenge 1 How to instantiate GW?

Idea 2: Reuse existing SLBs with unique locations

Challenge 2 How to perform atomic snapshot initiation for asynchronous GWs?

Idea 3: Optimistic Gateway Marking (OGM)

- Optimistic execution in common cases
- Verification/rejection of snapshot under worst cases

Key ideas in Beaver

How to ensure consistency without coordinating external machines?

More details about Beaver's protocol...

- Synchronization-free snapshot verification
- Supporting parallel snapshots
- Handling failures
- Handling packet loss, delay, and reordering
- •

Chanenge z now to nanote asynchronous Gws:

Idea 3: Optimistic Gateway Marking (OGM)

- Optimistic execution in common cases
- Verification/rejection of snapshot under worst cases

Implementation and evaluation

SLB-associated workflow

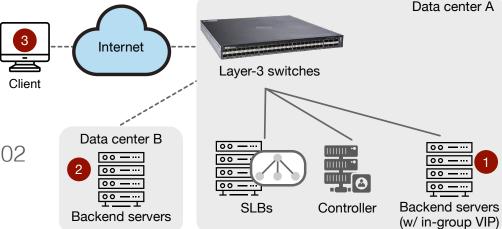
- Layer-3 ECMP forwarding per service VIPs: DELL EMC PowerSwitch S4048-ON
- Core SLB functions in DPDK: ~1860 LoC
- Backend server functions in XDP and tc: ~1040 LoC

Beaver protocol integration

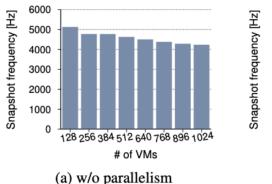
 Minimal logic: (1) 68 LoC for SLB DPDK data path logic (2) 102 LoC for eBPF at in-group VMs

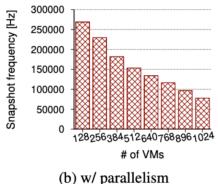
Topology

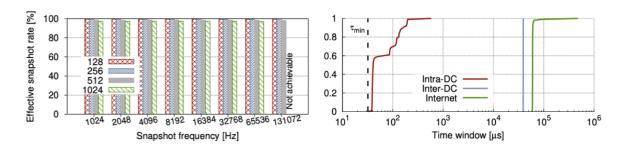
- Support typical communication patterns
- Possible out-group locations: within the same DC, DC at a different region, or on the Internet
- Scale up to 16 SLB servers and 1024 backend applications



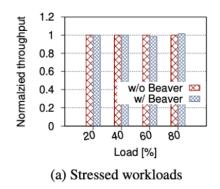
Details in the paper…

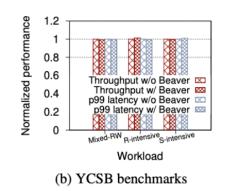






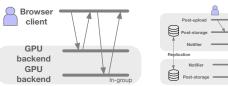
Beaver supports fast snapshot rates

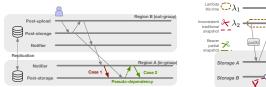




Beaver incurs zero impact

Beaver rejects snapshots infrequently

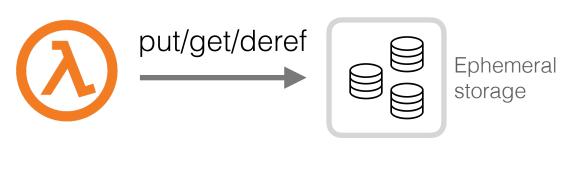






Use cases: integration testing, service analytics, deadlock detection, garbage collection...

Example: garbage collection for ephemeral storage

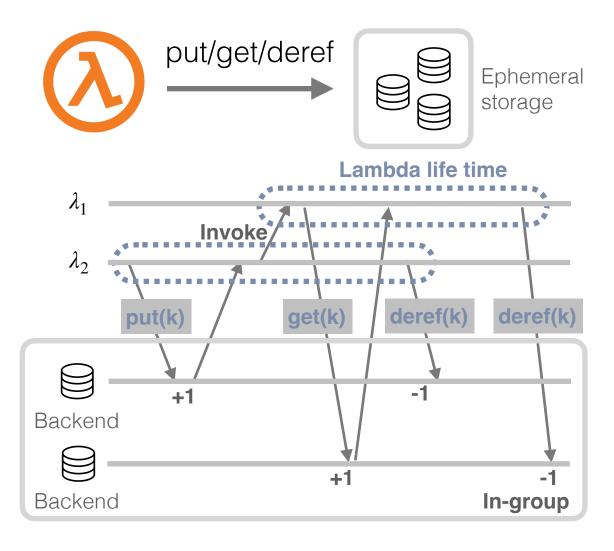


 λ_1

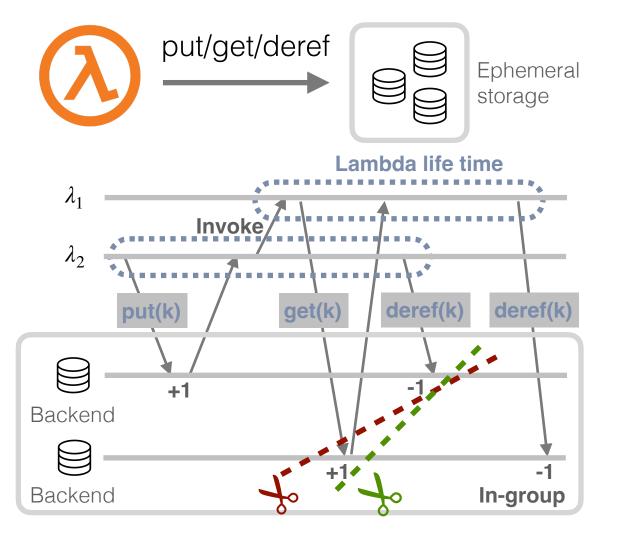
 λ_2



Example: garbage collection for ephemeral storage



Example: garbage collection for ephemeral storage



Strawman

Reference count = 0, unsafe recycle decision of k!



Reference count = 1, safe decision recognizing open reference to k

Beaver: summary

The first partial snapshot protocol that extends classic distributed snapshots in **practical cloud settings**

Guarantees causal consistency while incurring minimal changes and overheads

Key idea: Exploit data center characteristics (e.g., unique topologies)

Vision: toward zero-waste networked systems



Insatiable application demand



Increasing energy consumption



Embodied carbon is also a major contributor!



Grand challenge: Push the wastes in computing infrastructure to their limits

Vision: toward zero-waste networked systems



Tight coupling IDLE resources, e.g., for performant network control

- Can we repurpose the underutilized resources for integrating network tasks?
- Or, how to reduce the wasted consumption to its limits (e.g., power)?



Restructuring systems stacks for efficient 'tax' functions

- Can we enable an asynchronous IDLE channel for executing tax functions?
- How to exploit the growing heterogeneity in hardware accelerators?



Rethinking classic layering principle for a clean-slate redesign

- How to specialize the stack leveraging the predictability in emerging workloads/primitives?
- Can we simplify and break the current layering architecture while ensuring modularity?
- Beyond cross-layer design, what does that 'post-layering' architecture look like?